



İSTANBUL KEMERBURGAZ ÜNİVERSİTESİ

Solaris I/O Management and Disk Scheduling

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Solaris I/O Management and Disk Scheduling

General Categories :

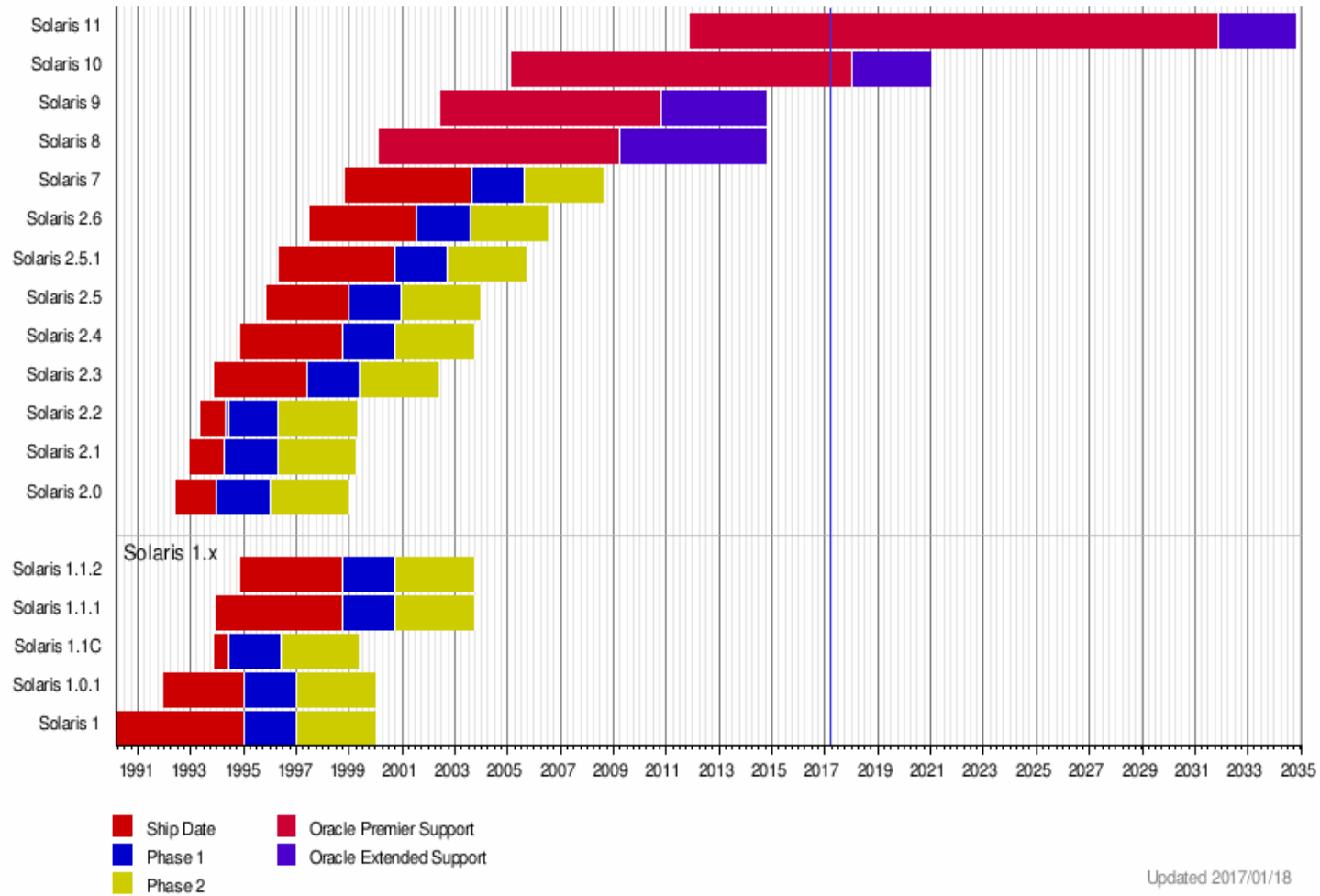
The I/O system consists of:

- 1-A buffer-caching system
- 2-A general device-driver interface
- 3- Drivers for specific hardware devices

Solaris

- Solaris is a Unix operating system originally developed by Sun Microsystems. It superseded their earlier SunOS in 1993. Oracle Solaris, so named as of 2010, has been owned by Oracle Corporation since the Sun acquisition by Oracle in January 2010.
- Solaris is known for its scalability, especially on SPARC systems, and for originating many innovative features such as DTrace, ZFS and Time Slider. Solaris supports SPARC-based and x86-based workstations and servers from Oracle and other vendors, with efforts underway to port to additional platforms. Solaris is registered as compliant with the Single Unix Specification .

Solaris Release Timeline



Why Study Operating Systems?

- Understand the relationship between hardware & software
- Understand future Operating Systems
- Understand powerful tools to help you in your computer use



Categories of I/O Devices

- Machine readable
 - Used to communicate with electronic equipment
 - Disk drives
 - USB keys
 - Sensors
 - Controllers
 - Actuators

Relationship Among Techniques

| | No Interrupts | Use of Interrupts |
|--|----------------|----------------------------|
| I/O-to-memory transfer through processor | Programmed I/O | Interrupt-driven I/O |
| Direct I/O-to-memory transfer | | Direct memory access (DMA) |

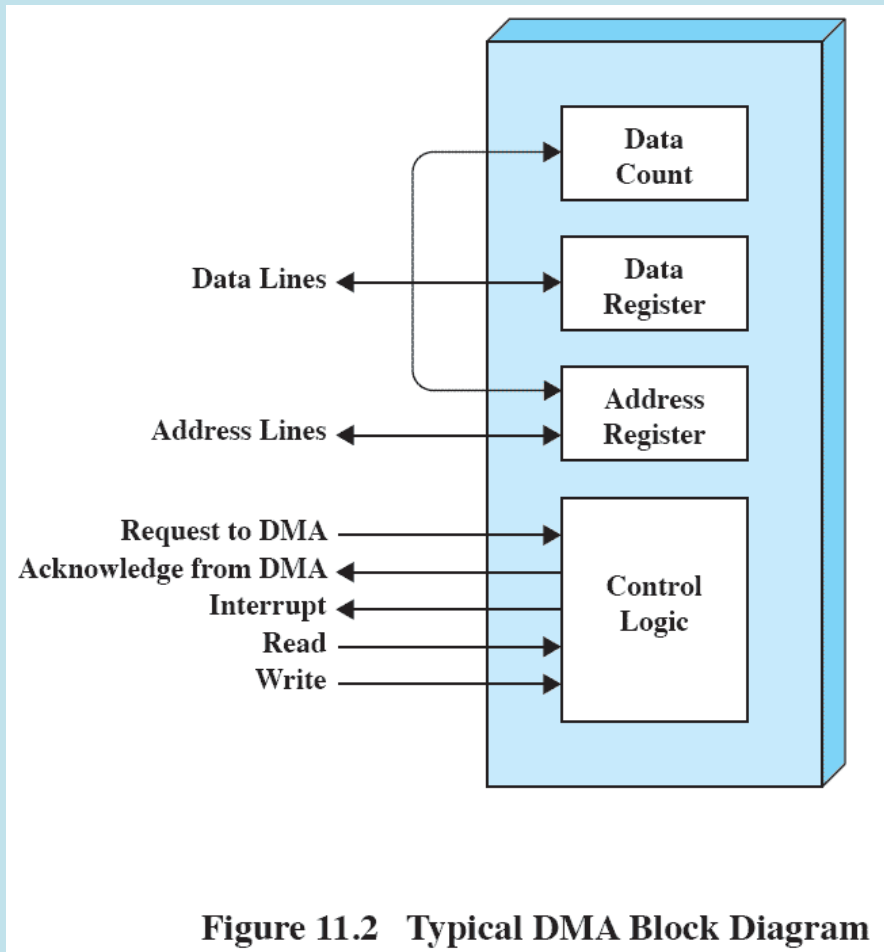
Evolution of the I/O Function

1. Processor directly controls a peripheral device .
2. A controller or I/O module is added .
3. Same configuration as step 2, but now interrupts are employed .
4. The I/O module is given direct control of memory via DMA .
5. The I/O module is enhanced to become a separate processor, with a specialized instruction set tailored for I/O .
6. The I/O module has a local memory of its own and is, in fact, a computer in its own right .

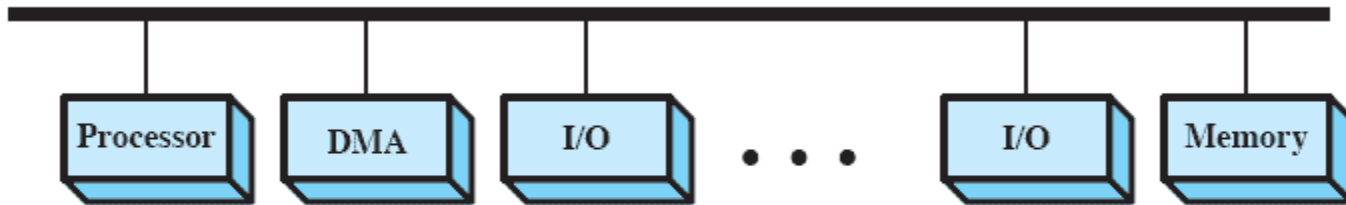
Direct Memory Address

- Processor delegates I/O operation to the DMA module
- DMA module transfers data directly to or from memory
- When transfer is complete, DMA module sends an interrupt signal to the processor

DMA

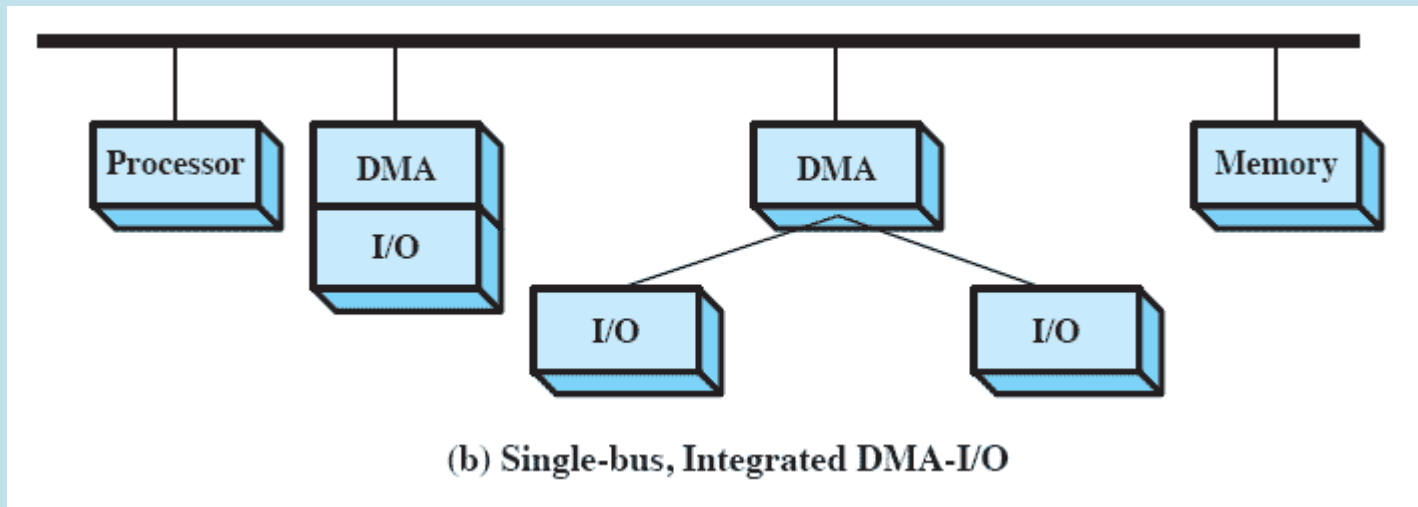


DMA Configurations

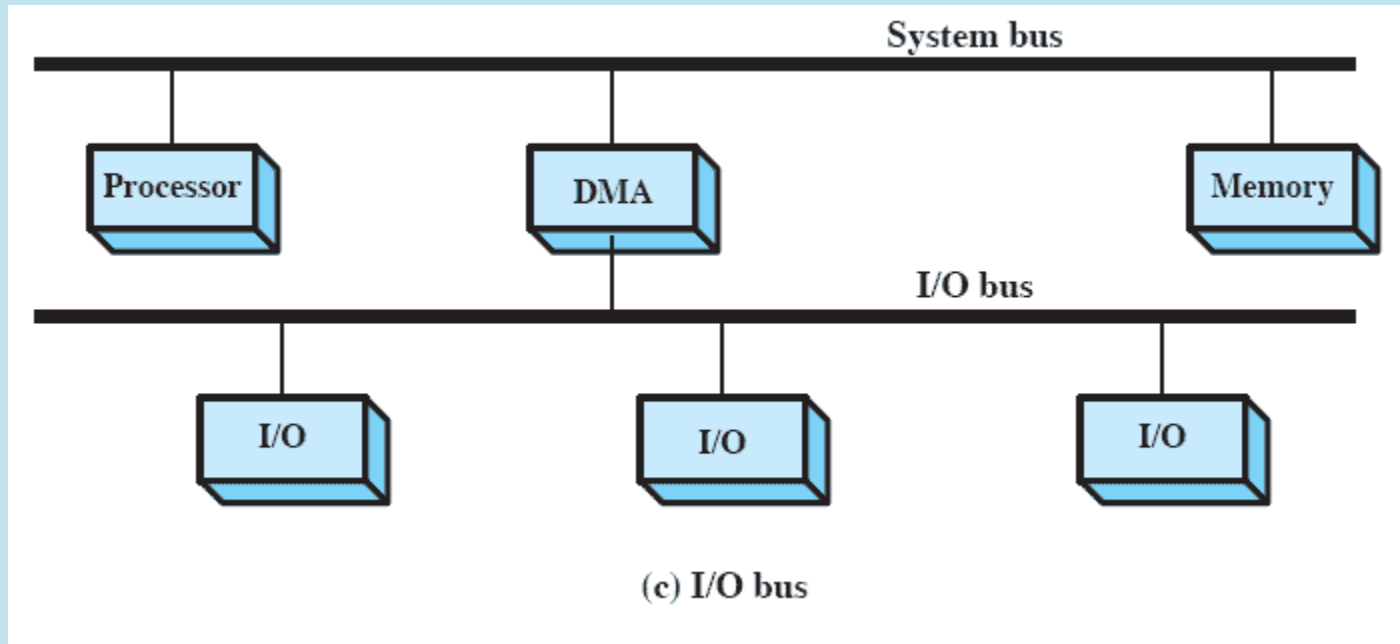


(a) Single-bus, detached DMA

DMA Configurations



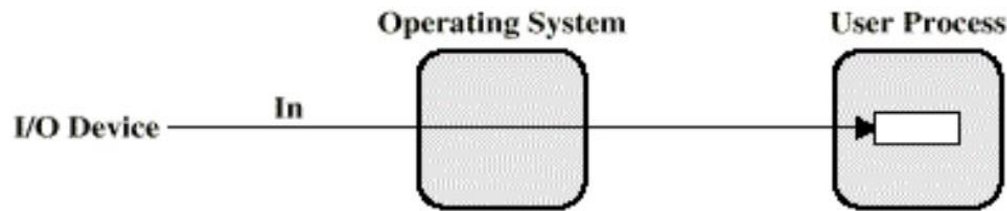
DMA Configurations



I/O Buffering

- Block-oriented
 - Information is stored in fixed sized blocks
 - Transfers are made a block at a time
 - Used for disks and USB keys
- Stream-oriented
 - Transfer information as a stream of bytes
 - Used for terminals, printers, communication ports, mouse and other pointing devices, and most other devices that are not secondary storage

NO BUFFERING



(a) No buffering

- **Process must read/write a device a byte/word a time.**
- **Each individual system call adds significant overhead.**
- **Process must wait until each I/O is complete.**
 - i) Blocking/waking adds to overhead
 - ii) Many short runs of a process is inefficient.
- **What happens if buffer is paged out to disk**
 - i) Could lose data while buffer is paged in
 - ii) Could lock buffer in memory (needed for DMA), however many processes doing I/O reduce RAM available for paging.
 - iii) Can cause deadlock as RAM is limited

USER LEVEL BUFFERING

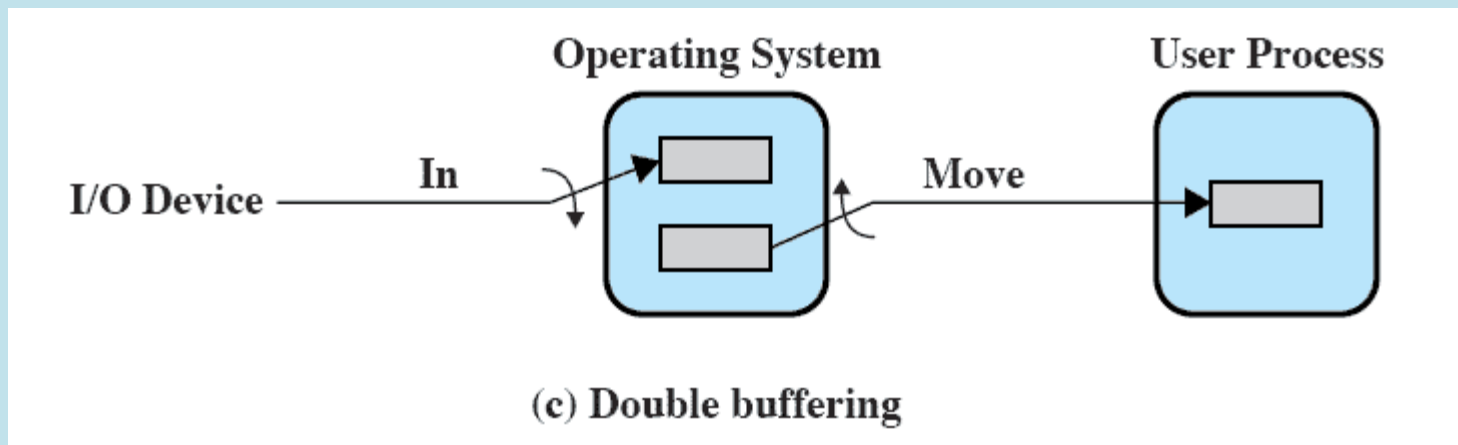
Clip slide

- User process can process one block of data while next block is read in.
- Swapping can occur since input is taking place in system memory, not user memory.
- Operating system keeps track of assignment of system buffers to user processes.
- Assume:
 - T is transfer time for a block from device
 - C is computation time to process incoming block
 - M is time to copy kernel buffer to user buffer

Computation and transfer can be done in parallel

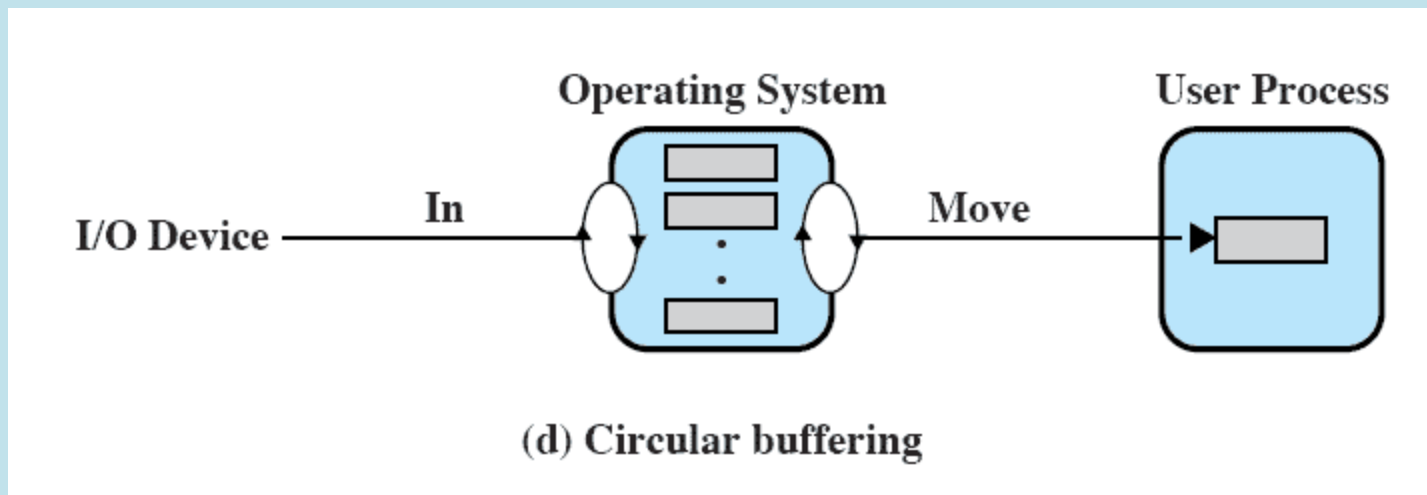
Double Buffer

- Use two system buffers instead of one
- A process can transfer data to or from one buffer while the operating system empties or fills the other buffer



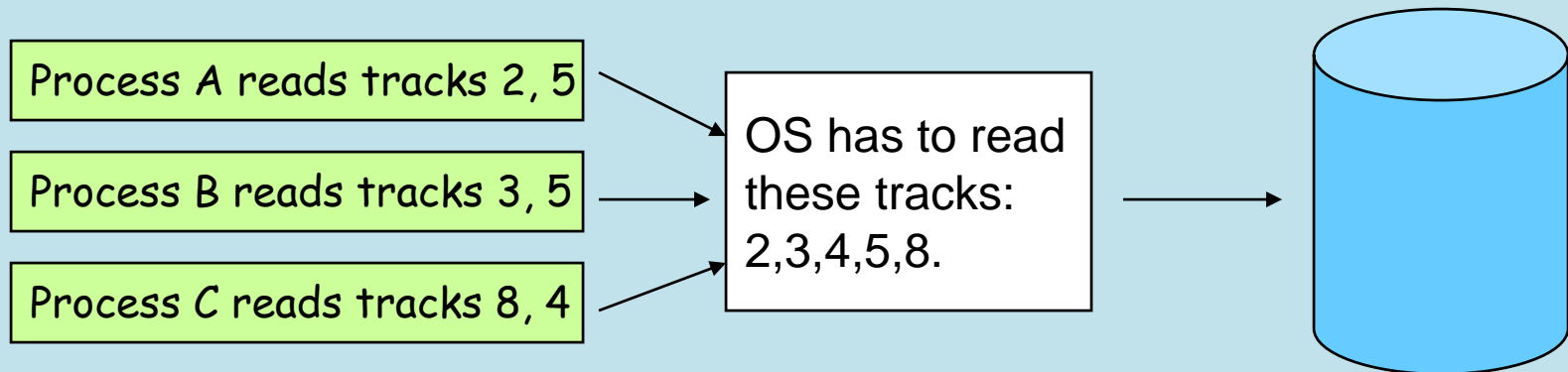
Circular Buffer

- More than two buffers are used
- Each individual buffer is one unit in a circular buffer
- Used when I/O operation must keep up with process



Disk Scheduling

- At runtime, I/O requests for disk tracks come from the processes
- OS has to choose an order to serve the requests

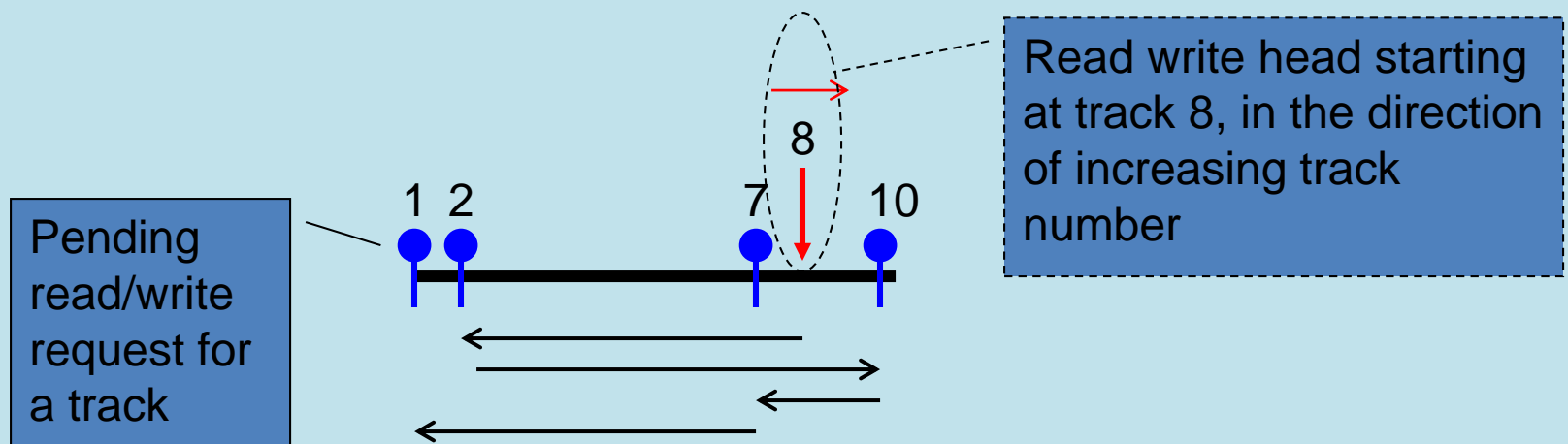


Disk Scheduling Policy

- FIFO: fair, but near random scheduling
- SSTF: possible starvation
- SCAN: favor requests for tracks near the ends
- C-SCAN
- FSCAN: avoid “arm stickiness” in SSTF, SCAN and C-SCAN

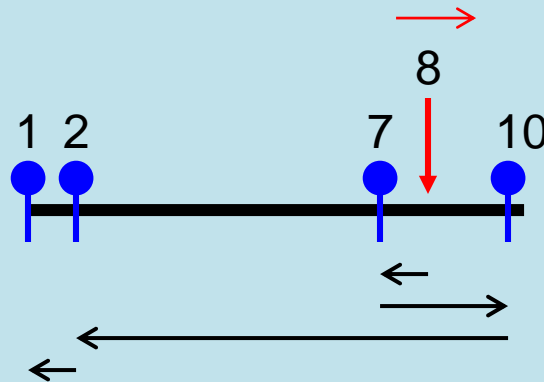
First-in-first-out, FIFO

- process requests in the order that the requests are made
- fair to all processes
- approaches random scheduling in performance if there are many processes



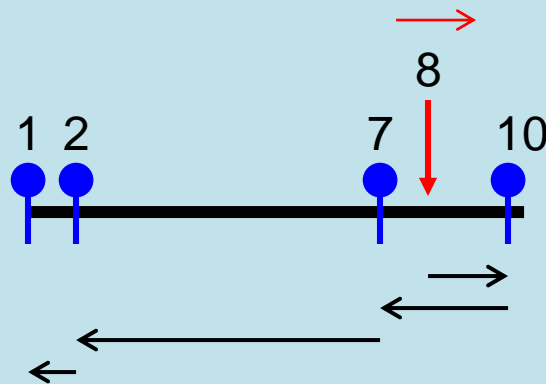
Shortest Service Time First, SSTF

- select the disk I/O request that requires the least movement of the disk arm from its current position
- always choose the minimum seek time
- new requests may be chosen before an existing request



SCAN

- arm moves in one direction only, satisfying all outstanding requests until there is no more requests in that direction. The service direction is then reversed.
- favor requests for tracks near the ends



FSCAN

- “Arm stickiness” in SSTF, SCAN, C-SCAN in case of repetitive requests to one track
- FSCAN uses two queues. When a SCAN begins, all of the requests are in one of the queues, with the other empty. During the scan, all new requests are put into the other queue.
- Service of new requests is deferred until all of the old requests have been processed.

Disk Scheduling Algorithms

| (a) FIFO (starting at track 100) | | (b) SSTF (starting at track 100) | | (c) SCAN (starting at track 100, in the direction of increasing track number) | | (d) C-SCAN (starting at track 100, in the direction of increasing track number) | |
|-------------------------------------|----------------------------------|-------------------------------------|----------------------------------|--|----------------------------------|--|----------------------------------|
| Next track accessed | Number of tracks traversed | Next track accessed | Number of tracks traversed | Next track accessed | Number of tracks traversed | Next track accessed | Number of tracks traversed |
| 55 | 45 | 90 | 10 | 150 | 50 | 150 | 50 |
| 58 | 3 | 58 | 32 | 160 | 10 | 160 | 10 |
| 39 | 19 | 55 | 3 | 184 | 24 | 184 | 24 |
| 18 | 21 | 39 | 16 | 90 | 94 | 18 | 166 |
| 90 | 72 | 38 | 1 | 58 | 32 | 38 | 20 |
| 160 | 70 | 18 | 20 | 55 | 3 | 39 | 1 |
| 150 | 10 | 150 | 132 | 39 | 16 | 55 | 16 |
| 38 | 112 | 160 | 10 | 38 | 1 | 58 | 3 |
| 184 | 146 | 184 | 24 | 18 | 20 | 90 | 32 |
| Average seek length | 55.3 | Average seek length | 27.5 | Average seek length | 27.8 | Average seek length | 35.8 |

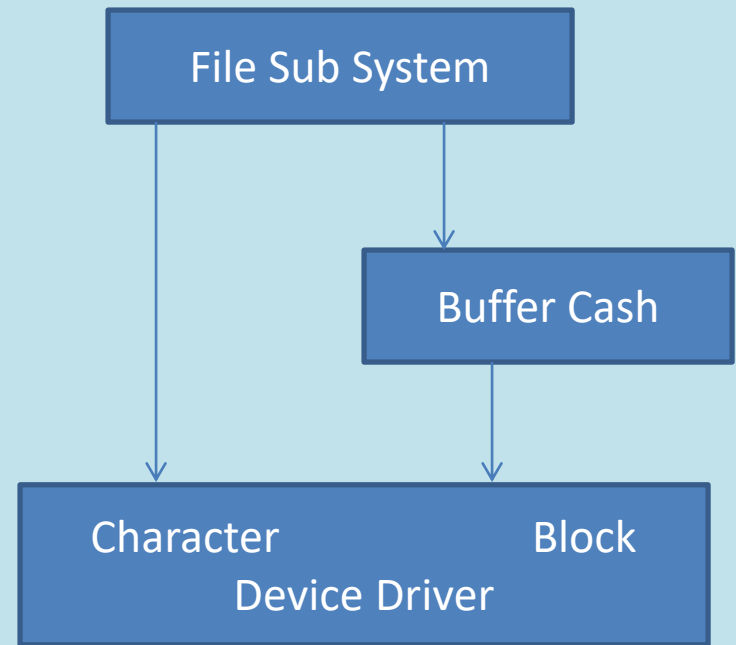
UNIX SVR4 I/O

Devices are Files

- Each I/O device is associated with a special file
 - Managed by the file system
 - Provides a clean uniform interface to users and processes.
- To access a device, read and write requests are made for the special file associated with the device.

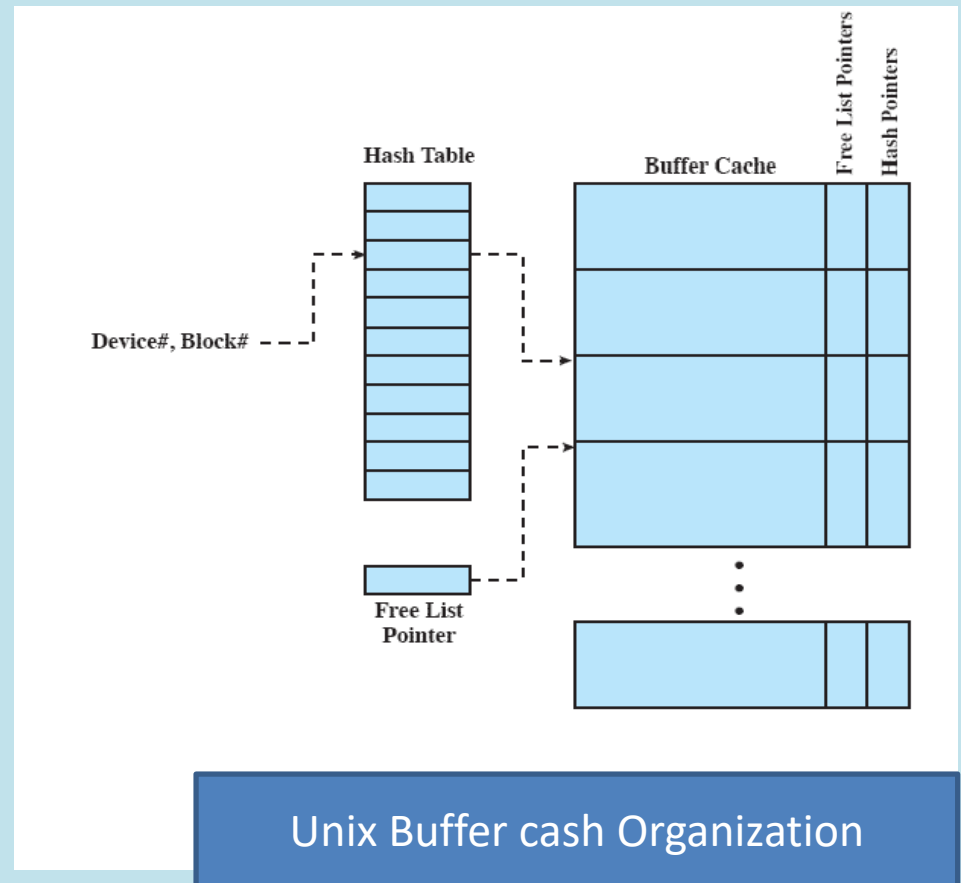
UNIX SVR4 I/O

- Each individual device is associated with a special file
- Two types of I/O
 - Buffered
 - Unbuffered



Buffer Cache

- Three lists are maintained
 - Free List
 - Device List
 - Driver I/O Queue



Character Cache

- Used by character oriented devices
 - E.g. terminals and printers
- Either written by the I/O device and read by the process or vice versa
 - Producer/consumer model used

Unbuffered I/O

- Unbuffered I/O is simply DMA between device and process
 - Fastest method
 - Process is locked in main memory and can't be swapped out
 - Device is tied to process and unavailable for other processes

I/O for Device Types

Unix

Device I/O in UNIX

| | Unbuffered I/O | Buffer Cache | Character Queue |
|----------------------------|-----------------------|---------------------|------------------------|
| Disk drive | X | X | |
| Tape drive | X | X | |
| Terminals | | | X |
| Communication lines | | | X |
| Printers | X | | X |

Thank you for my listening