

# Dekker's algorithms for Semaphores Implementation

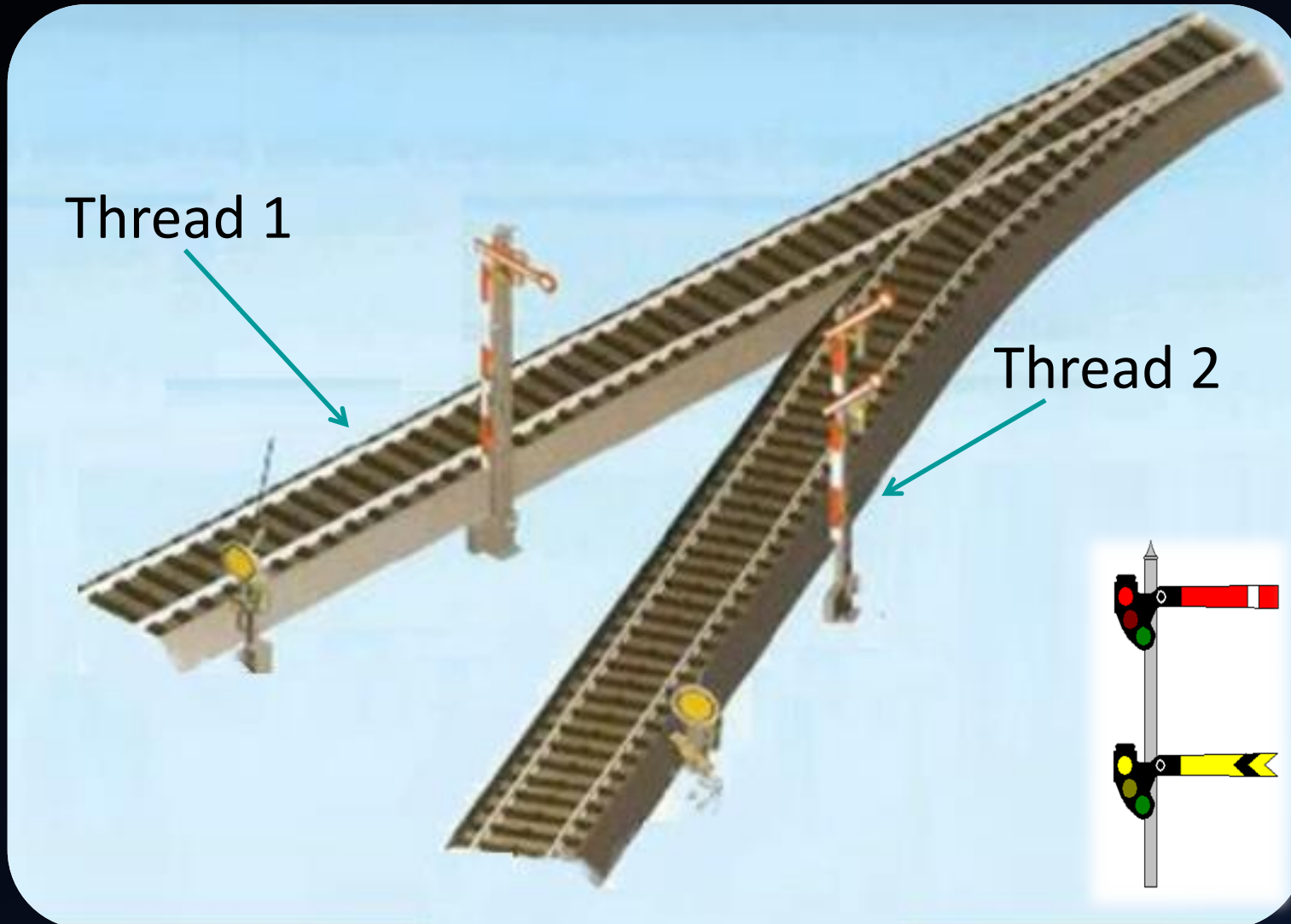


ALI TARIQ AL-KHAYYAT ( 163101413 )  
Submitted to : Prof. Dr. Huseyin Balik

# OUTLINES

- what is Dekker's algorithm.
- Dekker's General algorithms.
- What is Semaphores.
- Semaphores implementation.
- Semaphore Implementation Busy waiting.
- semaphores implementation for solving critical section by mutual exclusion.

# WHAT IS DEKKER'S ALGORITHMS ?



Dekker adds the idea of a favored thread and allows access to either thread when the request is uncontested

Flag represent  
Favored Thread

# DEKKER'S ALGORITHMS

- Dekker's algorithm is the first known correct solution to the mutual exclusion problem in concurrent programming, Dutch mathematician Dekker by Dijkstra .
- It allows two threads to share a single-use resource without conflict, using only shared memory for communication.
- If two processes attempt to enter a critical section at the same time, the algorithm will allow only one process in, based on whose turn it is, If one process is already in the critical section.
- the other process will busy wait for the first process to exit, This is done by the use of two flags, `wants_to_enter[0]` and `wants_to_enter[1]` , which indicate an intention to enter the critical section on the part of processes 0 and 1, respectively.

# DEKKER'S GENERAL ALGORITHMS

```
variables
  wants_to_enter : array of 2 booleans
  turn : integer
```

```
wants_to_enter[0] ← false
wants_to_enter[1] ← false
turn ← 0 // or 1
```

```
p0:
  wants_to_enter[0] ← true
  while wants_to_enter[1] {
    if turn ≠ 0 {
      wants_to_enter[0] ← false
      while turn ≠ 0 {
        // busy wait
      }
      wants_to_enter[0] ← true
    }
  }

  // critical section
  ...
  turn ← 1
  wants_to_enter[0] ← false
  // remainder section
```

```
p1:
  wants_to_enter[1] ← true
  while wants_to_enter[0] {
    if turn ≠ 1 {
      wants_to_enter[1] ← false
      while turn ≠ 1 {
        // busy wait
      }
      wants_to_enter[1] ← true
    }
  }

  // critical section
  ...
  turn ← 0
  wants_to_enter[1] ← false
  // remainder section
```

# DEKKER'S ALGORITHM

- Assumes two threads, numbered 0 and 1

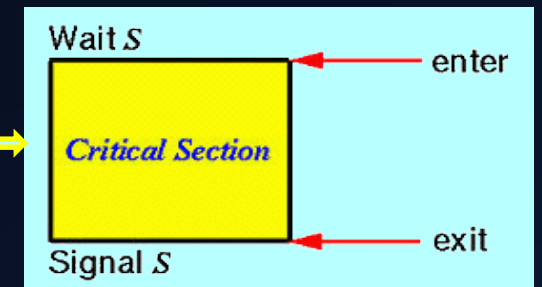
**CS**Enter(int i)

```
{
  inside[i] = true;
  while(inside[J])
  {
    if (turn == J)
    {
      inside[i] = false;
      while(turn == J) continue;
      inside[i] = true;
    }
  }
}
```

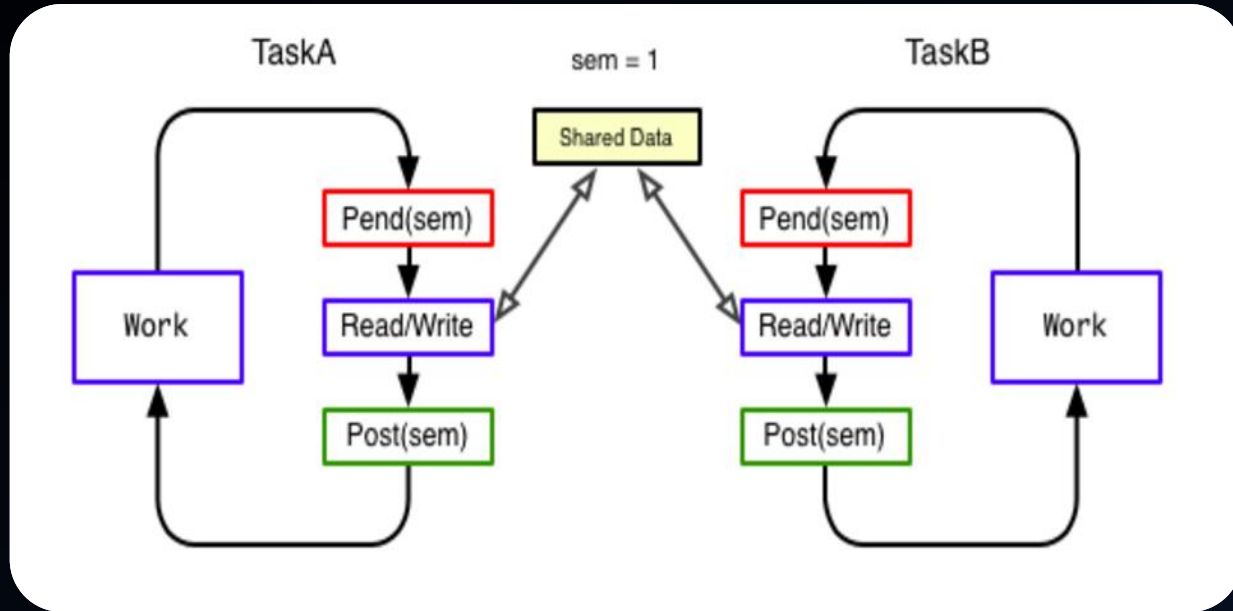
**CS**Exit(int i)

```
{
  turn = J;
  inside[i] = false;
}
```

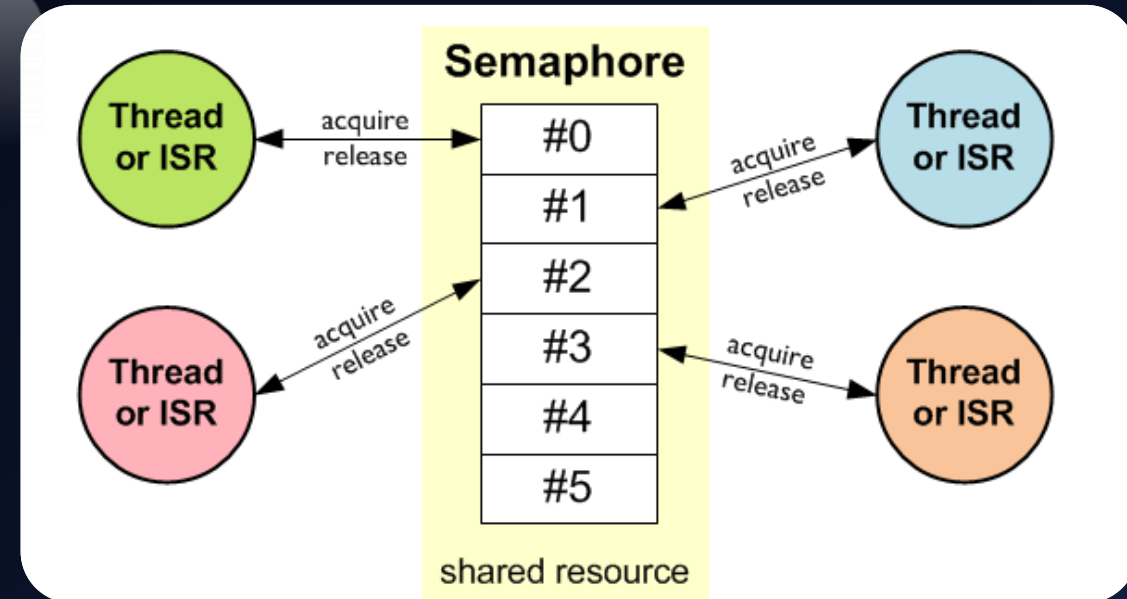
critical section →



# SEMAPHORES



- If a process is waiting for a signal, it is suspended until that signal is sent.
- **Wait and Signal operations cannot be interrupted.**
- A queue is used to hold processes waiting on the semaphore.



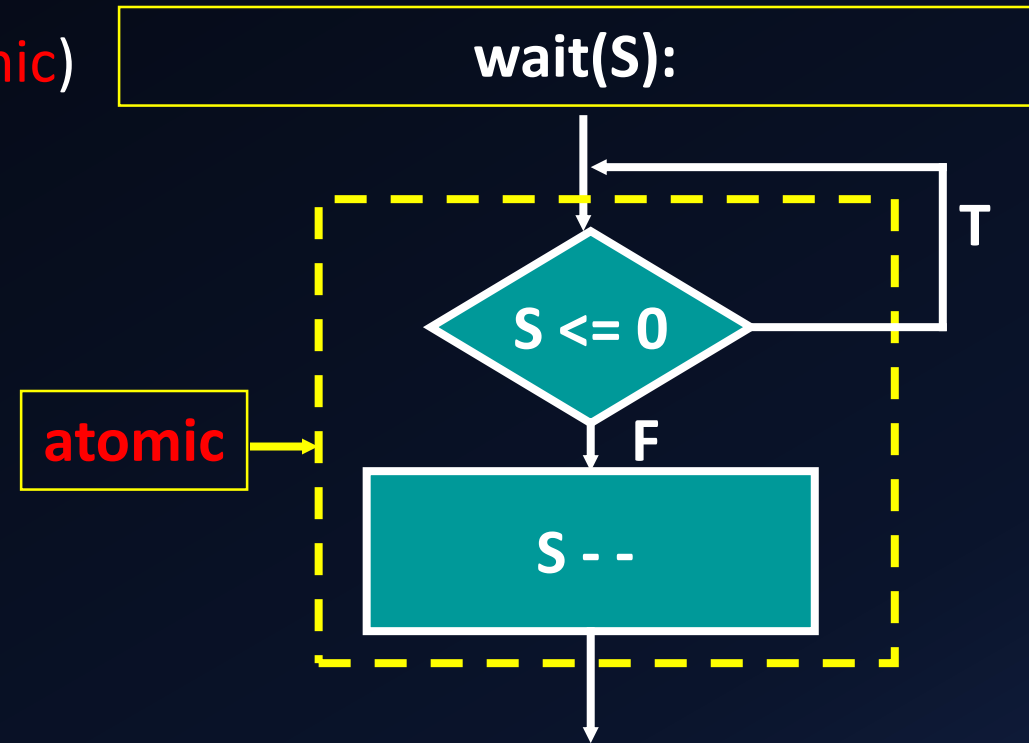
*atomic and mutually exclusive*



# SEMAPHORES

- Synchronization tool that does not require busy waiting , Semaphore is an integer flag, indicated that it is safe to proceed.
- Two standard operations modify S: wait() and signal()
  - Originally called P() and V() , Less complicated.
- Can only be accessed via two indivisible (**atomic**) operations.

```
wait (S) {  
    while S <= 0  
        ; // no-op  
        S--;  
}  
signal (S) {  
    S++;  
}
```





# SEMAPHORES IMPLEMENTATION

- Must guarantee that no two processes can execute wait () and signal () on the same semaphore at the same time.
- Thus, implementation becomes the critical section problem where the wait and signal code are placed in the critical section.
  - Could now have busy waiting in critical section implementation
    - But implementation code is short
    - Little busy waiting if critical section rarely occupied
- Note that applications may spend lots of time in critical sections and therefore this is not a good solution.

# SEMAPHORE IMPLEMENTATION BLOCK AND WAKEUP

- With each semaphore there is an associated waiting queue. Each entry in a waiting queue has two data items:
  - value (of type integer)
  - pointer to next record in the list
- Two operations:
  - **block** – place the process invoking the operation on the suitable waiting queue.
  - **wakeup** – remove one of processes in the waiting queue and place it in the ready queue.

# SEMAPHORE IMPLEMENTATION WITH BUSY WAITING

- Implementation of **wait**:

```
wait (S){  
    value--;  
    if (value < 0) {  
        add this process to waiting queue  
        block(); }    }
```

- Implementation of **signal**:

```
Signal (S){  
    value++;  
    if (value <= 0) {  
        remove a process P from the waiting queue  
        wakeup(P); }    }
```

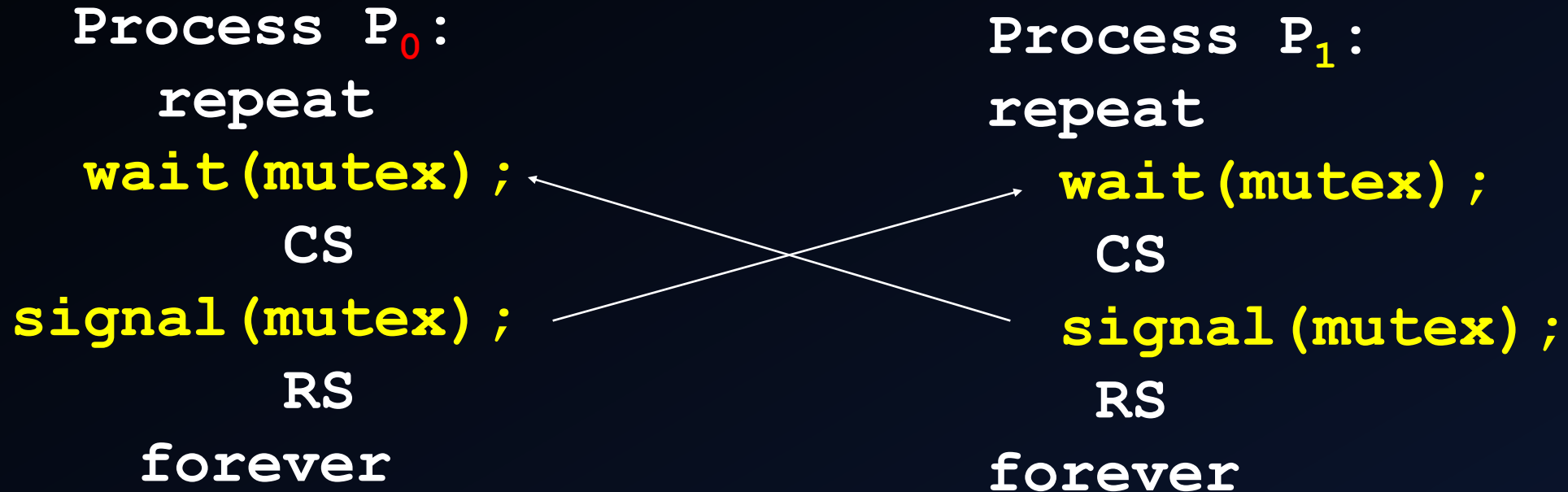
# SEMAPHORES IMPLEMENTATION FOR SOLVING CRITICAL SECTION BY MUTUAL EXCLUSION

- For n processes
- Initialize semaphore "mutex" to 1
- Then only one process is allowed into CS (**mutual exclusion**)
- To allow 2 processes into CS at a time, simply initialize mutex to 2

```
Process P0:  
repeat  
    wait(mutex) ;  
    CS  
    signal(mutex) ;  
    RS  
forever
```

# SEMAPHORES IN ACTION

Initialize **mutex** to 1



# THE REFERENCES

[https://en.wikipedia.org/wiki/Dekker%27s\\_algorithm](https://en.wikipedia.org/wiki/Dekker%27s_algorithm)

- “Operating Systems”, William Stallings, ISBN 0-13-032986-X
- “Operating Systems – A modern perspective”, Garry Nutt, ISBN 0-8053-1295-1