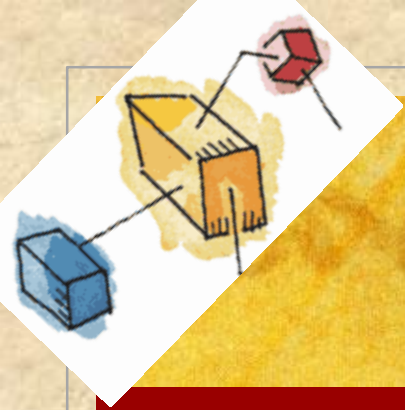


IT 540 Operating Systems

ECE519 Advanced Operating Systems

Prof. Dr. Hasan Hüseyin BALIK

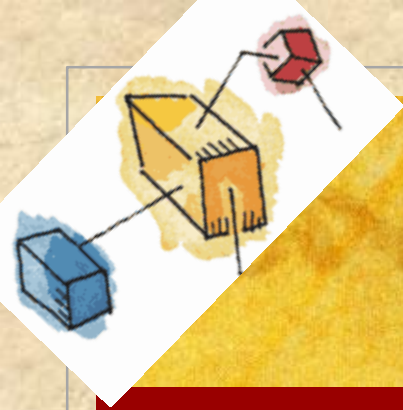
(1st Week)



Outline

- Course Information and Policies
- Course Syllabus
- 1. Computer System Overview





Course Information

- Instructor: Prof. Dr. Hasan H. BALIK, balik@yildiz.edu.tr, hasanbalik@gmail.com and www.hasanbalik.com

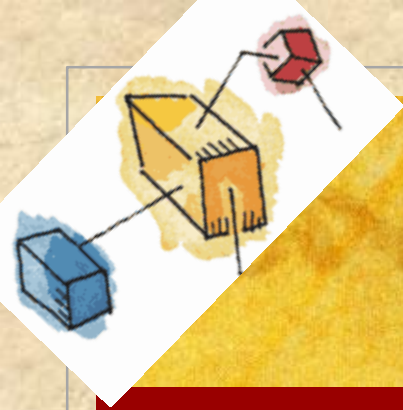
- Class Homepage:

<http://www.hasanbalik.com/LectureNotes/OpSys/>

Book: Operating Systems, 8th Edition, William Stallings, Prentice Hall 2015

- Grading: Assingment 50% and Final 50%

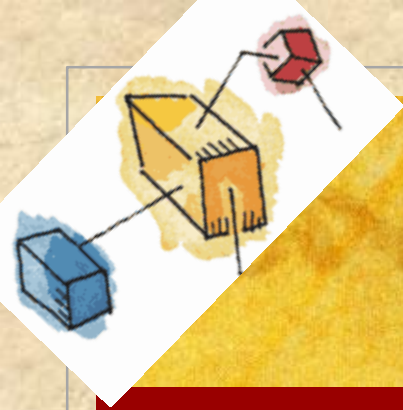




Course Syllabus-1

- Computer System Overview
- Operating System Overview
- Process Description and Control
- Threads
- Concurrency: Mutual Exclusion and Synchronization
- Concurrency: Deadlock and Starvation
- Memory Management





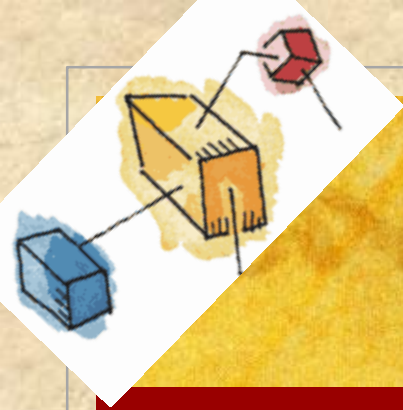
Course Syllabus-2

- Virtual Memory
- Uniprocessor Scheduling
- Multiprocessor and Real-Time Scheduling
- I/O Management and Disk Scheduling
- File Management
- Embedded Operating Systems



*(Advanced)
Operating
Systems*

1. Computer System Overview



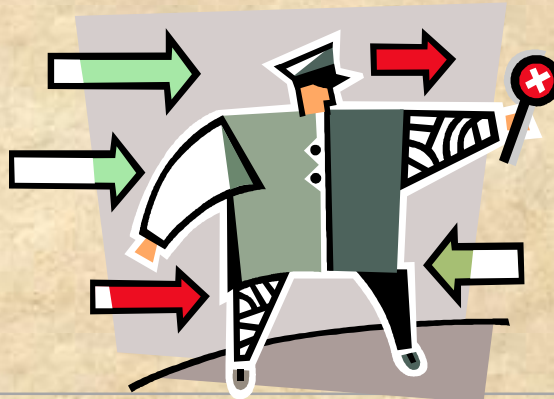
1. Outline

- Basic Elements
- Evolution of the Microprocessor
- Instruction Execution
- Interrupts
- The Memory Hierarchy
- Cache Memory
- Direct Memory Access
- Multiprocessor and Multicore Organization



Operating System

- Exploits the hardware resources of one or more processors
- Provides a set of services to system users
- Manages secondary memory and I/O devices



Basic Elements

Processor

**I/O
Modules**

**Main
Memory**

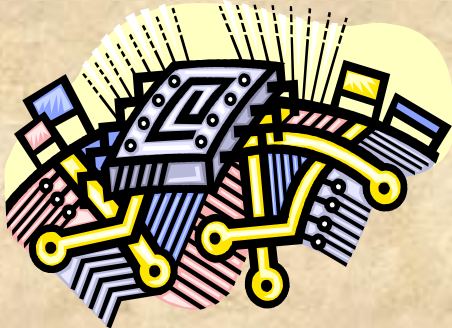
**System
Bus**



Processor

Controls the
operation of the
computer

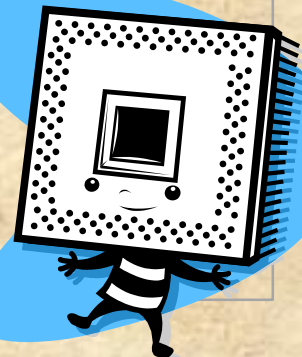
Performs the
data processing
functions



Referred to as
the *Central
Processing Unit*
(CPU)

Main Memory

- Volatile
- Contents of the memory is lost when the computer is shut down
- Referred to as real memory or primary memory



I/O Modules

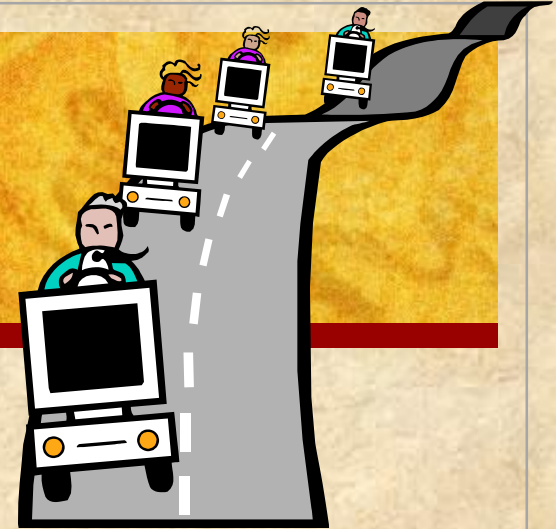
Moves data
between the
computer and
external
environments
such as:

storage (e.g. hard
drive)

communications
equipment

terminals

System Bus



- Provides for communication among processors, main memory, and I/O modules

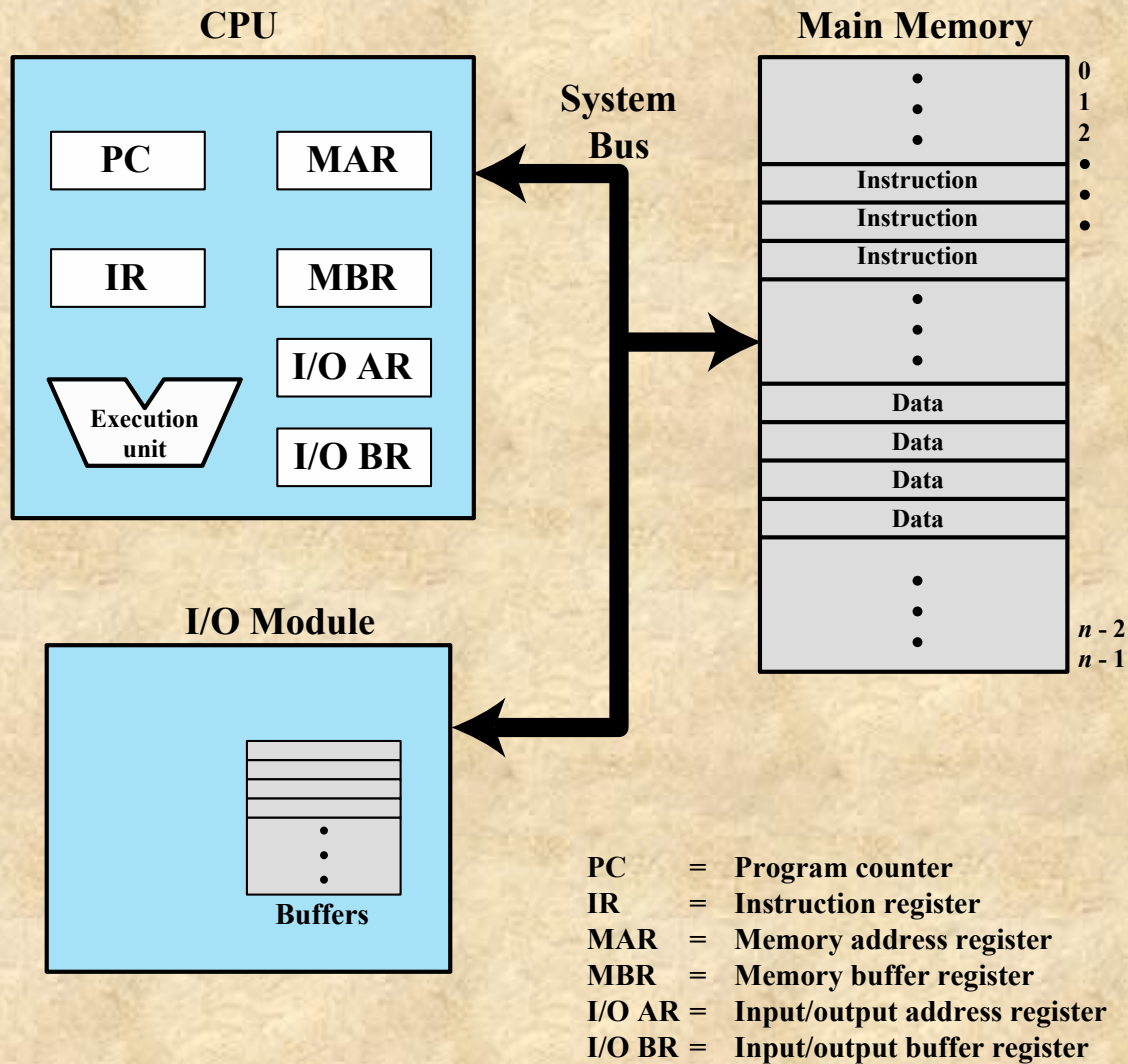
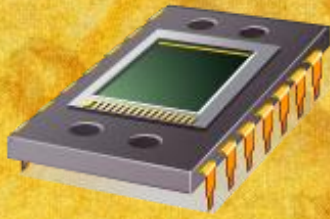


Figure 1.1 Computer Components: Top-Level View



Microprocessor

- Invention that brought about desktop and handheld computing
- Processor on a single chip
- Fastest general purpose processor
- Multiprocessors
- Each chip (socket) contains multiple processors (cores)

Graphical Processing Units (GPU's)

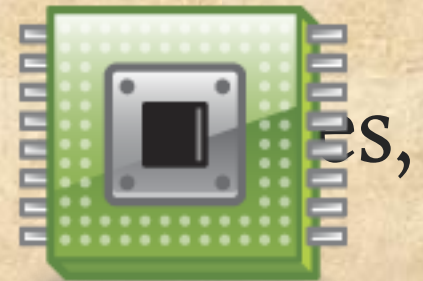
- Provide efficient computation on arrays of data using Single-Instruction Multiple Data (SIMD) techniques
- Used for general numerical processing
- Physics simulations for games
- Computations on large spreadsheets

Digital Signal Processors (DSPs)

- Deal with streaming signals such as audio or video
- Used to be embedded in devices like modems
- Encoding/decoding speech and video (codecs)
- Support for encryption and security

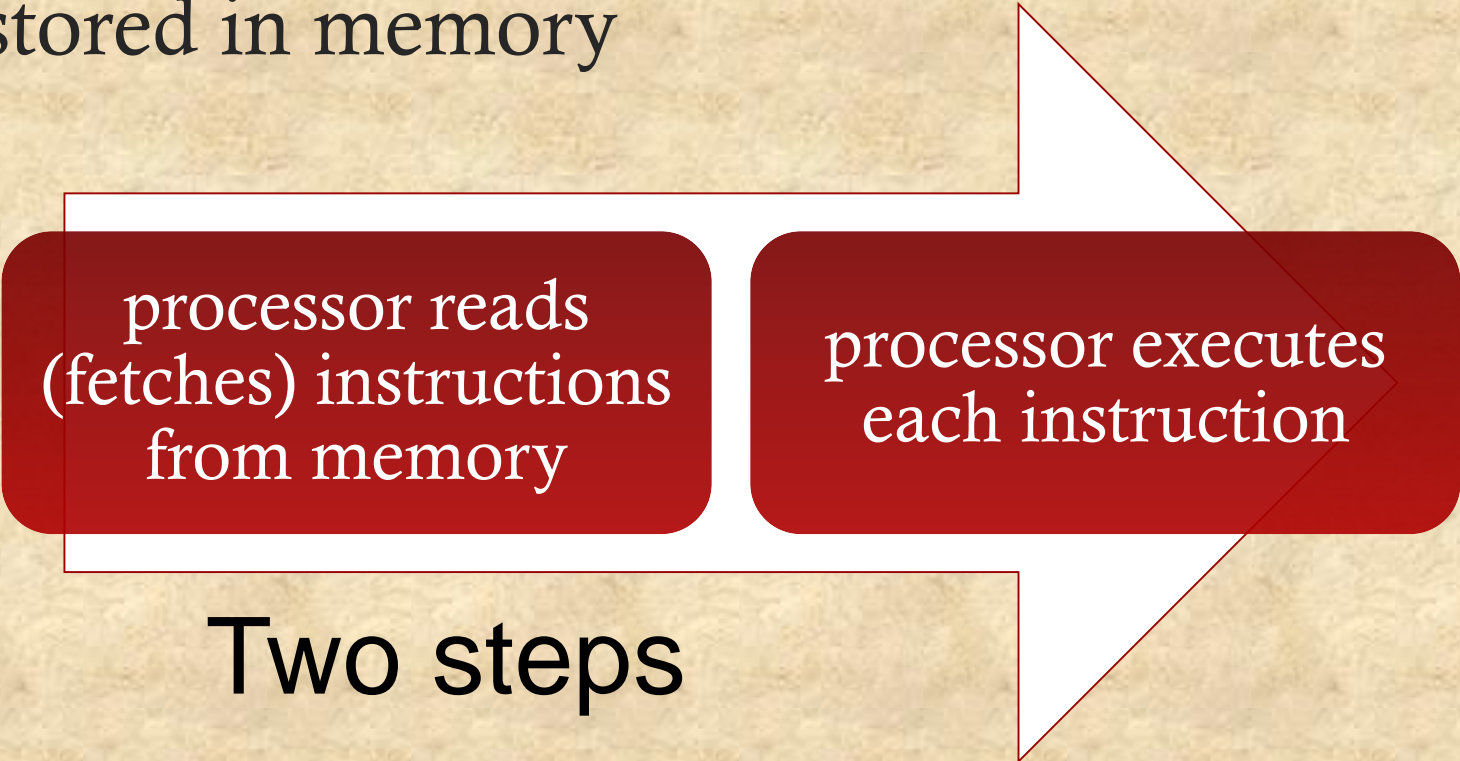
System on a Chip (SoC)

- To satisfy the requirements of handheld devices, the microprocessor is giving way to the SoC
- Components such as DSPs, GPUs, codecs and main memory, in addition to the CPUs and are on the same chip



Instruction Execution

- A program consists of a set of instructions stored in memory



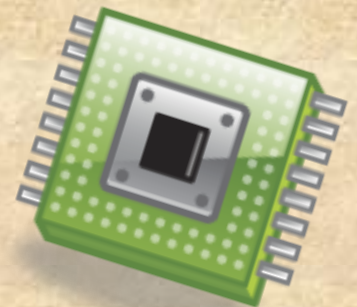
processor reads
(fetches) instructions
from memory

processor executes
each instruction

Two steps

Instruction Fetch and Execute

- The processor fetches the instruction from memory
- Program counter (PC) holds address of the instruction to be fetched next
 - PC is incremented after each fetch



Instruction Register (IR)

Fetches instruction is loaded into Instruction Register (IR)

■ Processor interprets the instruction and performs required action:

- Processor-memory
- Processor-I/O
- Data processing
- Control



Interrupts

- Interrupt the normal sequencing of the processor
- Provided to improve processor utilization
 - most I/O devices are slower than the processor
 - processor must pause to wait for device
 - wasteful use of the processor



Classes of Interrupts

Program	Generated by some condition that occurs as a result of an instruction execution, such as arithmetic overflow, division by zero, attempt to execute an illegal machine instruction, and reference outside a user's allowed memory space.
Timer	Generated by a timer within the processor. This allows the operating system to perform certain functions on a regular basis.
I/O	Generated by an I/O controller, to signal normal completion of an operation or to signal a variety of error conditions.
Hardware failure	Generated by a failure, such as power failure or memory parity error.

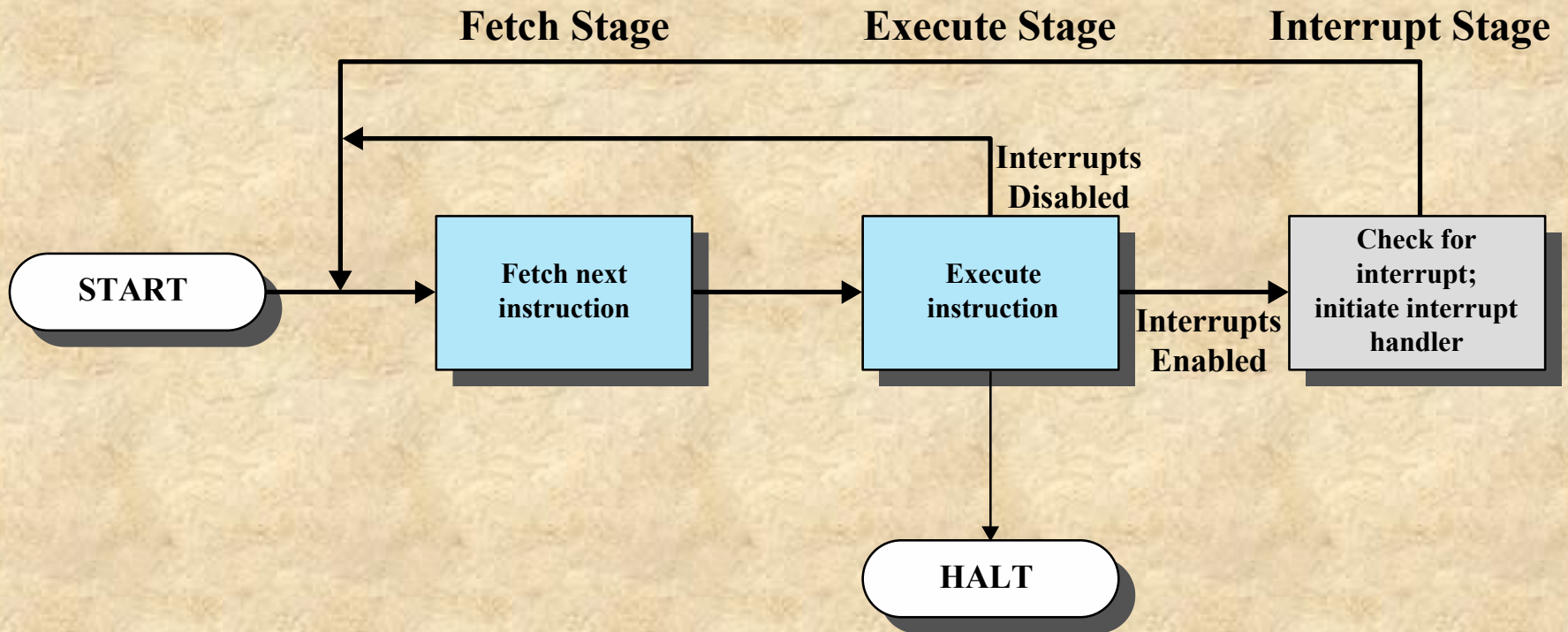


Figure 1.7 Instruction Cycle with Interrupts

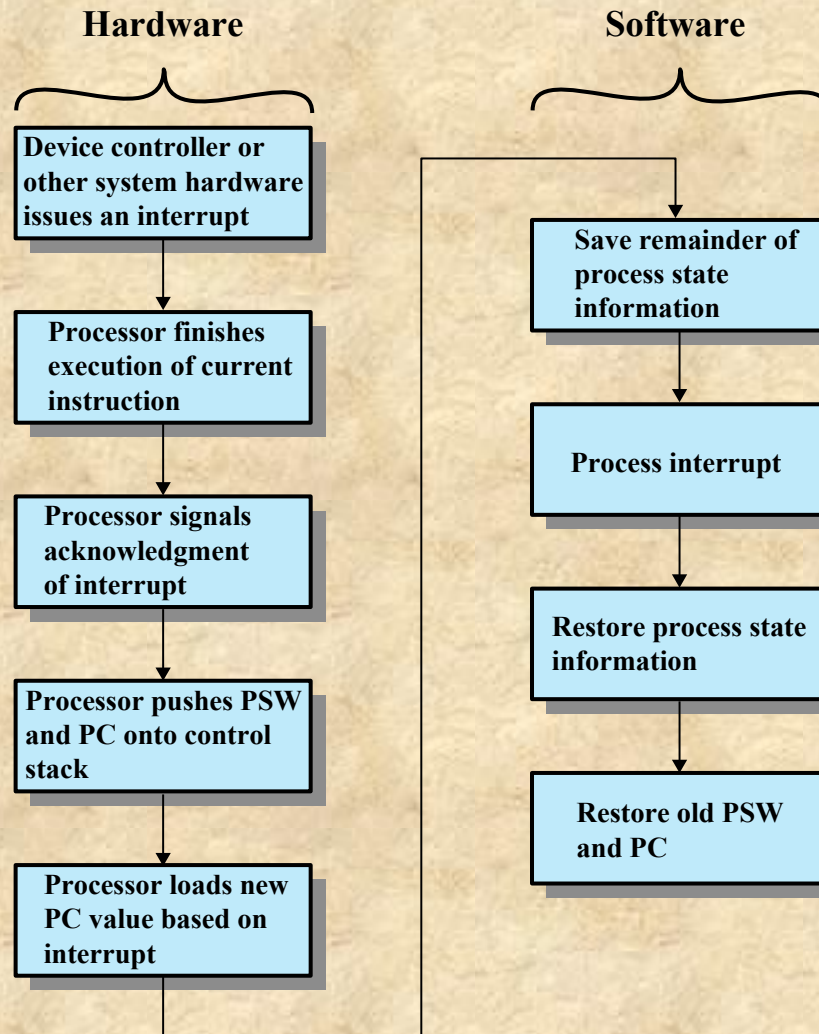


Figure 1.10 Simple Interrupt Processing

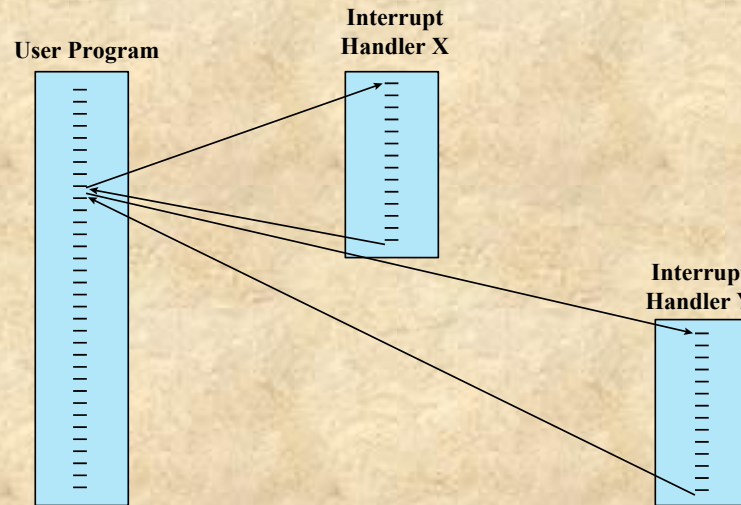
Multiple Interrupts

An interrupt occurs while another interrupt is being processed

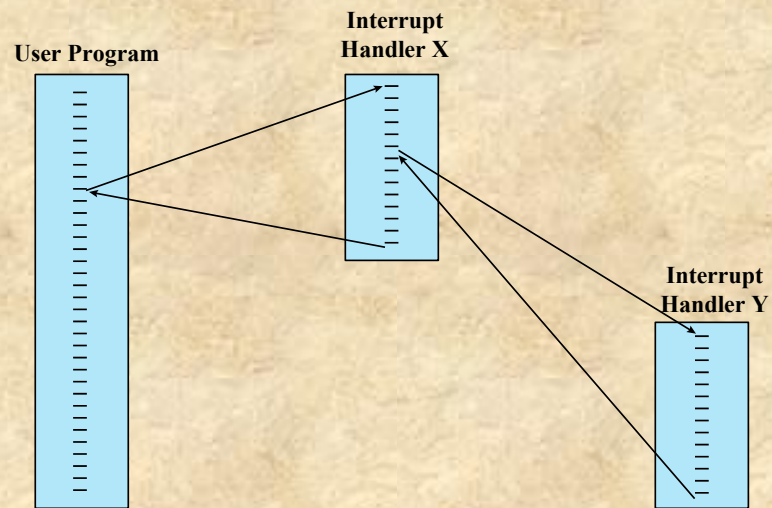
- e.g. receiving data from a communications line and printing results at the same time

Two approaches:

- disable interrupts while an interrupt is being processed
- use a priority scheme



(a) Sequential interrupt processing

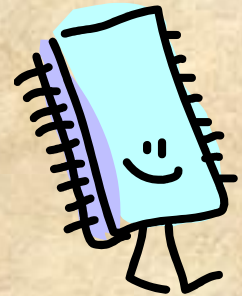


(b) Nested interrupt processing

Figure 1.12 Transfer of Control with Multiple Interrupts

Memory Hierarchy

- Major constraints in memory
 - amount
 - speed
 - expense
- Memory must be able to keep up with the processor
- Cost of memory must be reasonable in relationship to the other components



Memory Relationships

Faster
access time
= greater
cost per bit

Greater capacity
= smaller cost per
bit

Greater
capacity =
slower access
speed

```
graph LR; A[Faster access time = greater cost per bit] --> B[Greater capacity = smaller cost per bit]; B --> C[Greater capacity = slower access speed];
```


The Memory Hierarchy

- Going down the hierarchy:
 - decreasing cost per bit
 - increasing capacity
 - increasing access time
 - decreasing frequency of access to the memory by the processor

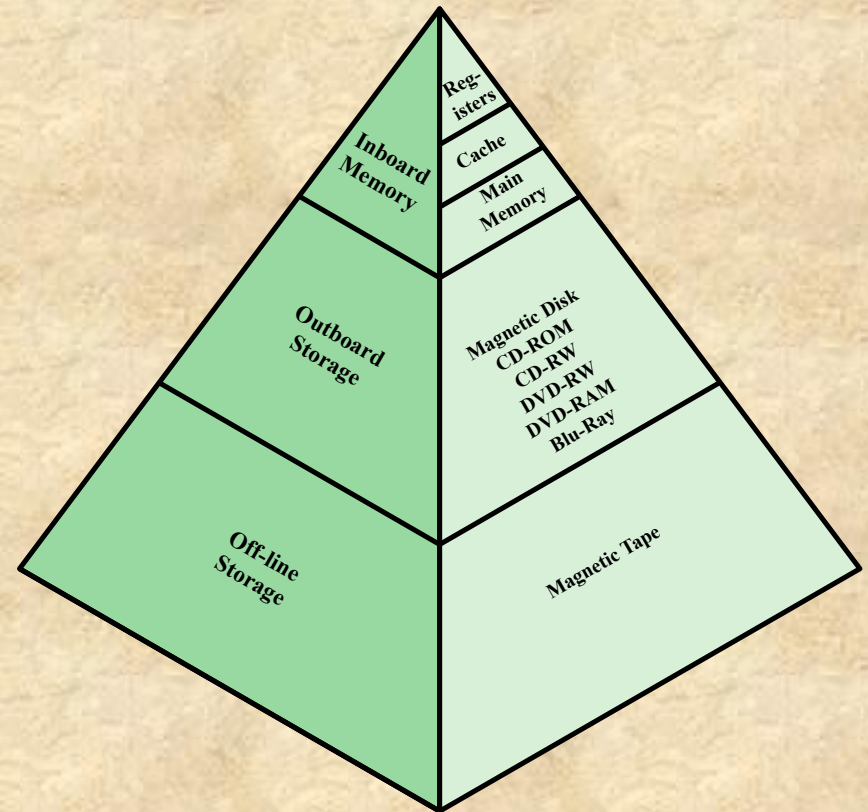


Figure 1.14 The Memory Hierarchy

Principle of Locality

- Memory references by the processor tend to cluster
- Data is organized so that the percentage of accesses to each successively lower level is substantially less than that of the level above
- Can be applied across more than two levels of memory

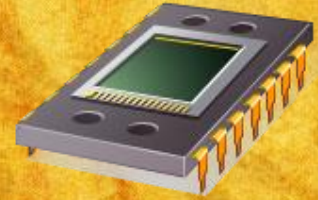
Secondary Memory



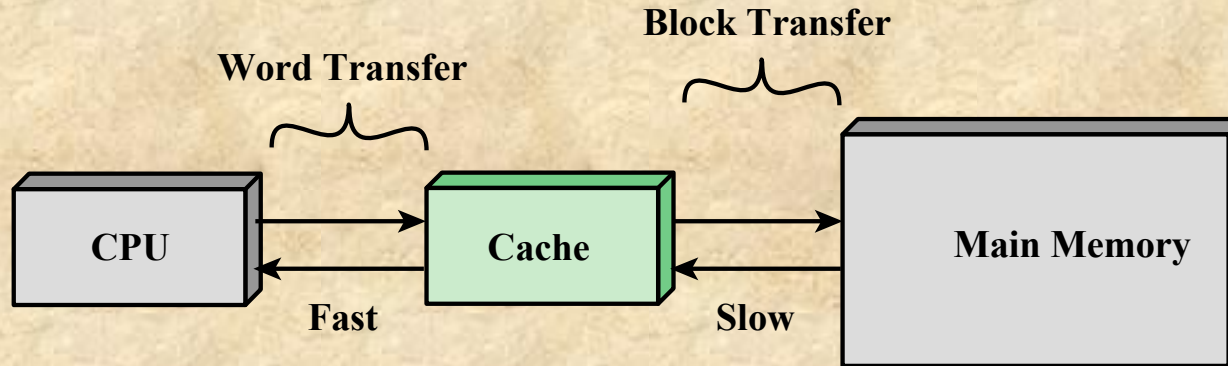
**Also referred to
as auxiliary
memory**

- external
- nonvolatile
- used to store
program and data
files

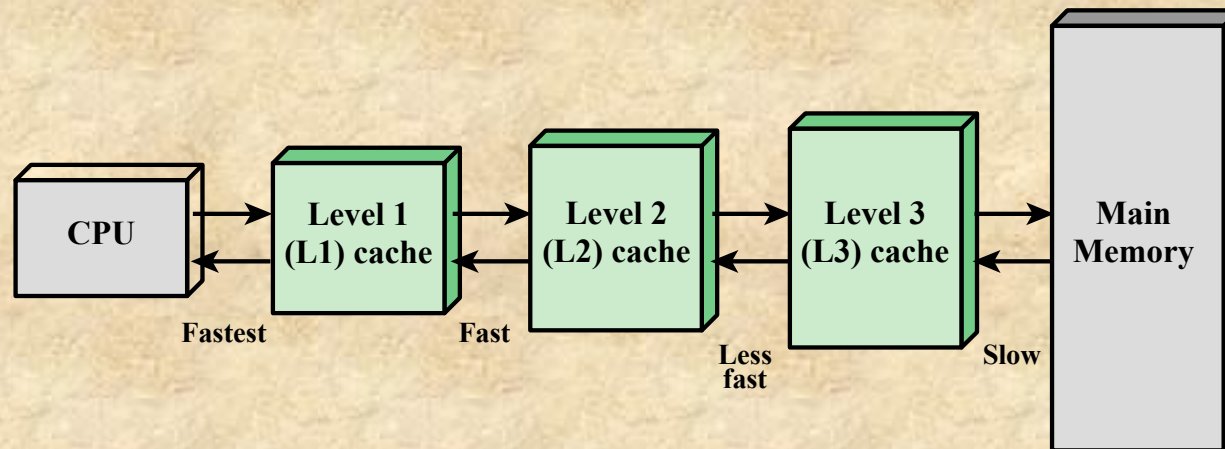
Cache Memory



- Invisible to the OS
- Interacts with other memory management hardware
- Processor must access memory at least once per instruction cycle
- Processor execution is limited by memory cycle time
- Exploit the principle of locality with a small, fast memory



(a) Single cache



(b) Three-level cache organization

Figure 1.16 Cache and Main Memory

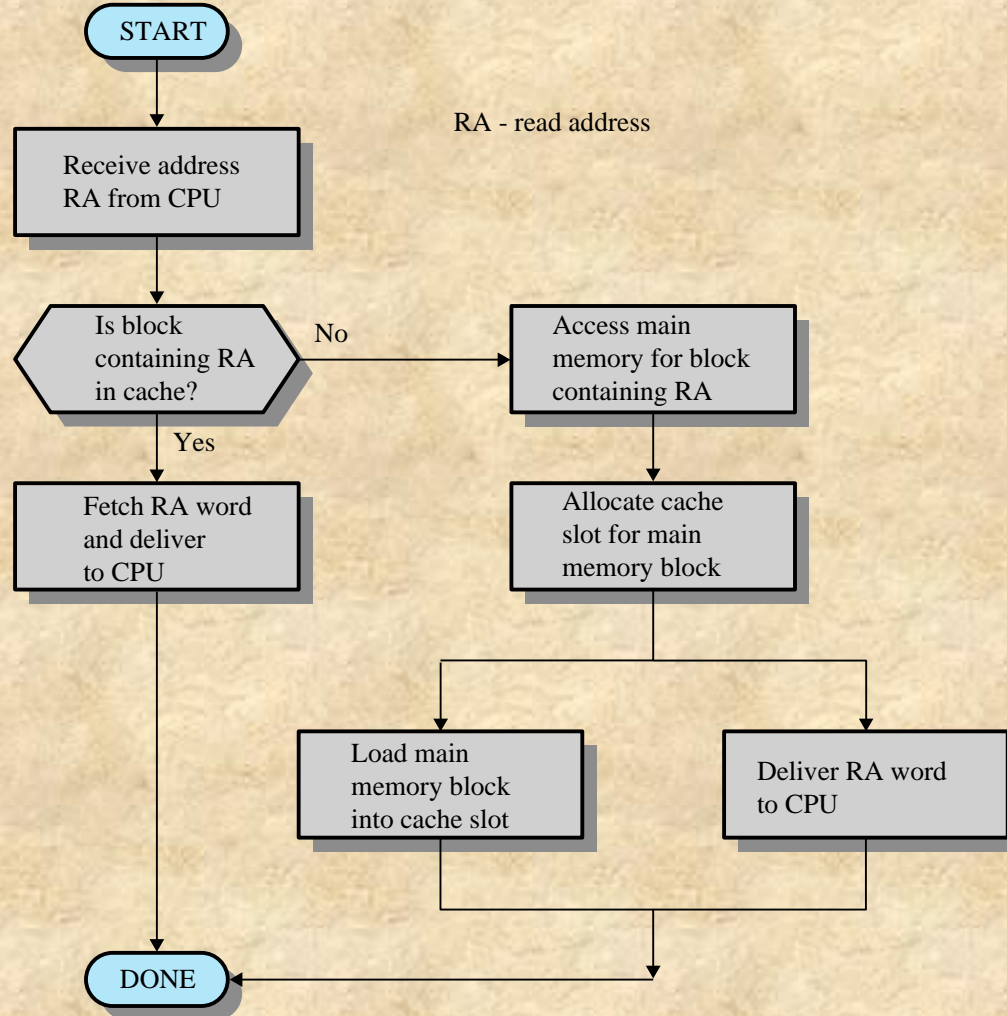
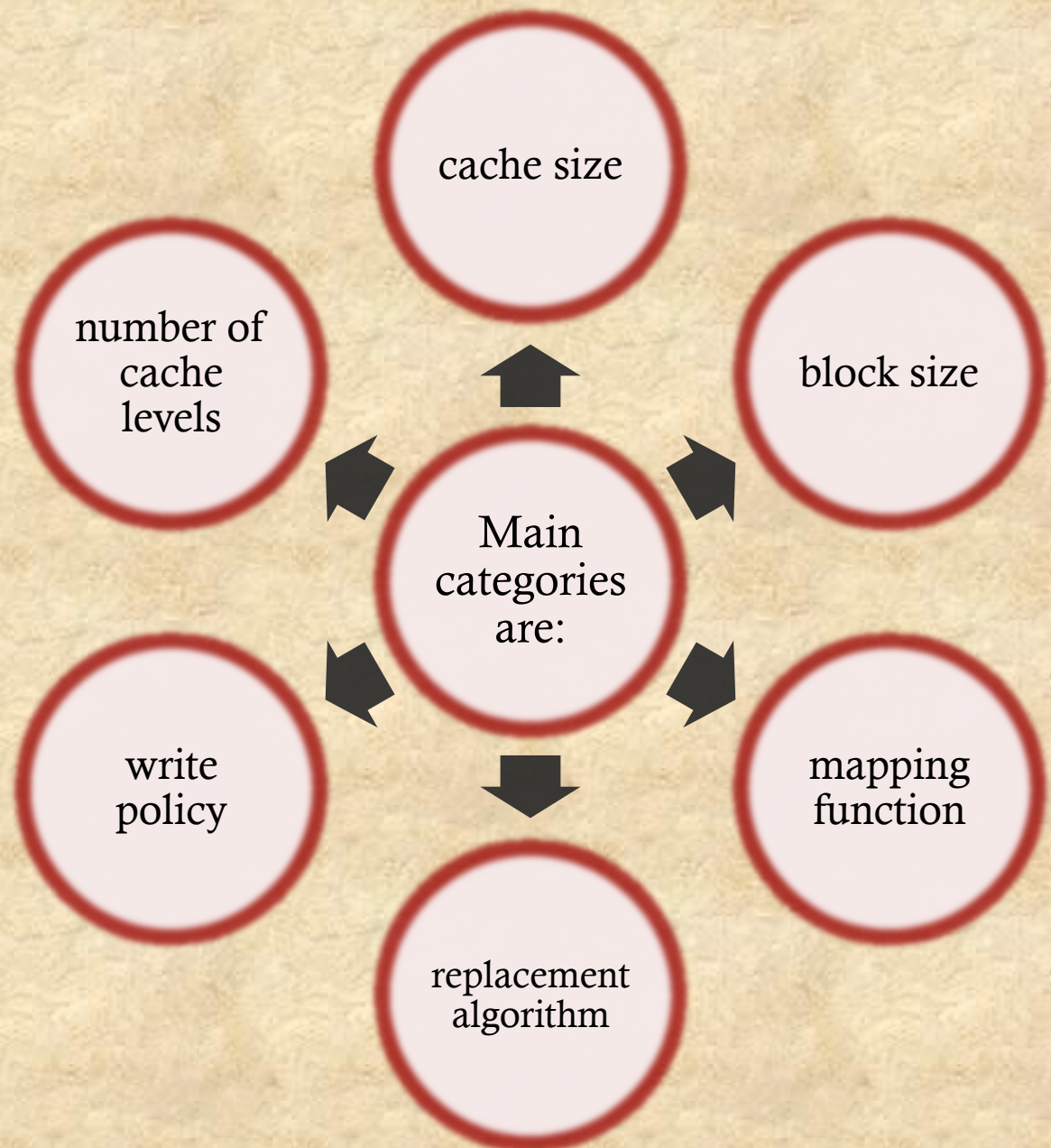


Figure 1.18 Cache Read Operation

Cache Design



Cache and Block Size

Cache Size

small caches have
significant impact
on performance

Block Size

the unit of data
exchanged
between cache and
main memory

Mapping Function

* Determines which cache location the block will occupy

Two constraints affect design:

when one block is read in, another may have to be replaced

the more flexible the mapping function, the more complex is the circuitry required to search the cache

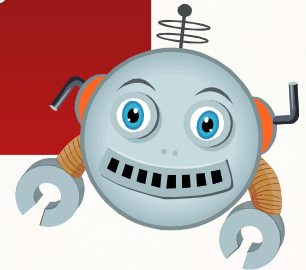
Replacement Algorithm

- Least Recently Used (LRU) Algorithm
 - effective strategy is to replace a block that has been in the cache the longest with no references to it
 - hardware mechanisms are needed to identify the least recently used block
 - chooses which block to replace when a new block is to be loaded into the cache

Write Policy

Dictates when the memory write operation takes place

- can occur every time the block is updated
- can occur when the block is replaced
 - minimizes write operations
 - leaves main memory in an obsolete state



I/O Techniques

* When the processor encounters an instruction relating to I/O, it executes that instruction by issuing a command to the appropriate I/O module

Three techniques are possible for I/O operations:

Programmed
I/O

Interrupt-
Driven I/O

Direct Memory
Access (DMA)

Programmed I/O

- The I/O module performs the requested action then sets the appropriate bits in the I/O status register
- The processor periodically checks the status of the I/O module until it determines the instruction is complete
- With programmed I/O the performance level of the entire system is severely degraded

Interrupt-Driven I/O

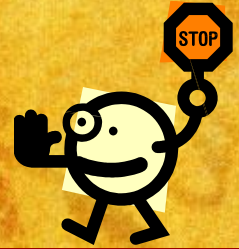
Processor issues an I/O command to a module and then goes on to do some other useful work

The processor executes the data transfer and then resumes its former processing

The I/O module will then interrupt the processor to request service when it is ready to exchange data with the processor

More efficient than Programmed I/O but still requires active intervention of the processor to transfer data between memory and an I/O module

Interrupt-Driven I/O Drawbacks



- Transfer rate is limited by the speed with which the processor can test and service a device
- The processor is tied up in managing an I/O transfer
 - a number of instructions must be executed for each I/O transfer

Direct Memory Access (DMA)

* Performed by a separate module on the system bus or incorporated into an I/O module

When the processor wishes to read or write data it issues a command to the DMA module containing:

- whether a read or write is requested
- the address of the I/O device involved
- the starting location in memory to read/write
- the number of words to be read/written

Direct Memory Access

- Transfers the entire block of data directly to and from memory without going through the processor
 - processor is involved only at the beginning and end of the transfer
 - processor executes more slowly during a transfer when processor access to the bus is required
- More efficient than interrupt-driven or programmed I/O

Symmetric Multiprocessors (SMP)



- A stand-alone computer system with the following characteristics:
 - two or more similar processors of comparable capability
 - processors share the same main memory and are interconnected by a bus or other internal connection scheme
 - processors share access to I/O devices
 - all processors can perform the same functions
 - the system is controlled by an integrated operating system that provides interaction between processors and their programs at the job, task, file, and data element levels

SMP Advantages

Performance

- a system with multiple processors will yield greater performance if work can be done in parallel

Scaling

- vendors can offer a range of products with different price and performance characteristics

Availability

- the failure of a single processor does not halt the machine

Incremental Growth

- an additional processor can be added to enhance performance

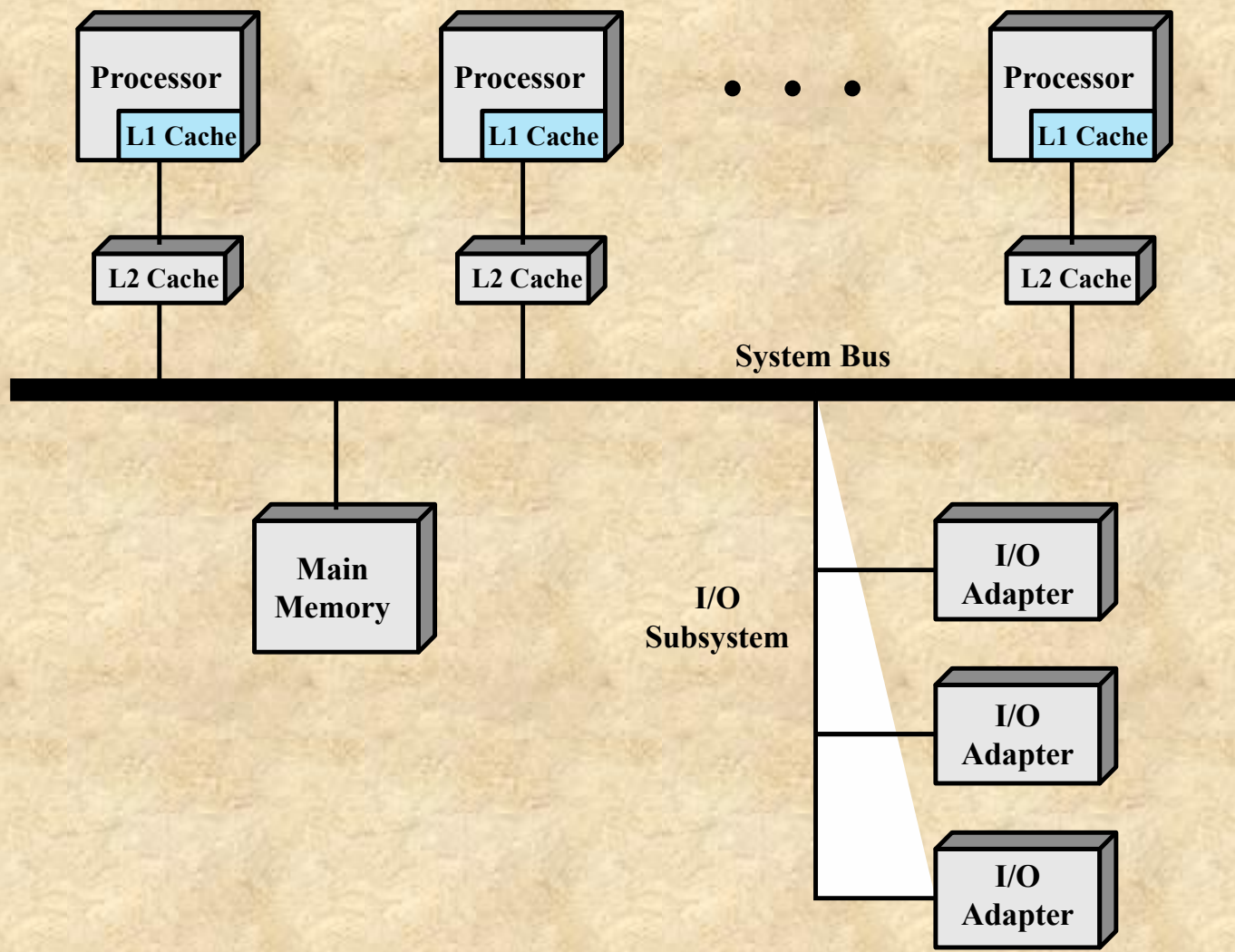
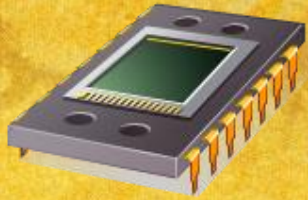


Figure 1.19 Symmetric Multiprocessor Organization



Multicore Computer

- Also known as a chip multiprocessor
- Combines two or more processors (cores) on a single piece of silicon (die)
 - each core consists of all of the components of an independent processor
- In addition, multicore chips also include L2 cache and in some cases L3 cache

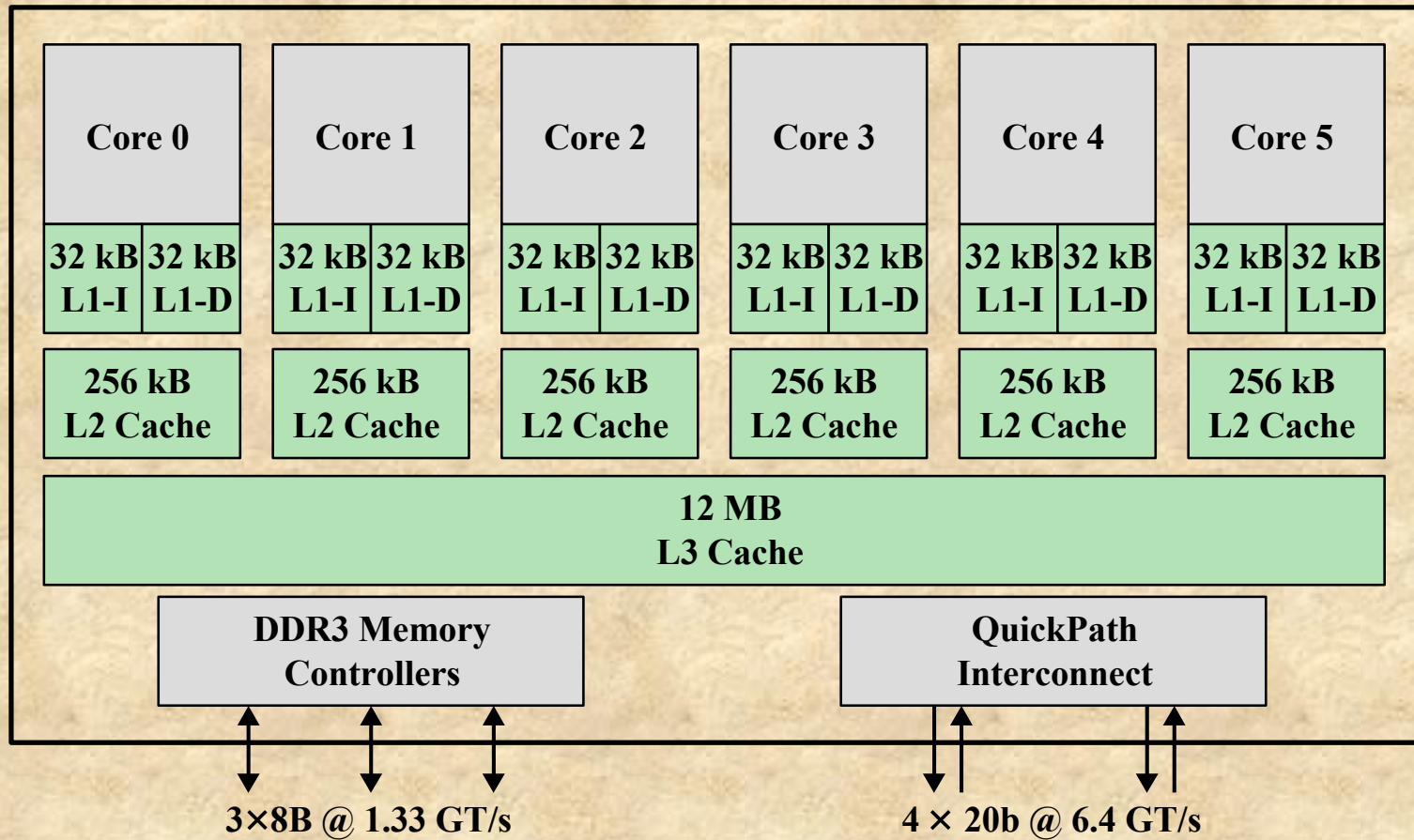


Figure 1.20 Intel Core i7-990X Block Diagram