

EEE321 Electromagnetic Fields and Waves

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(6th Week)

Outline

- Type of Magnetic Materials
- Magnetizasyon **M**
- Magnetic field Strength **H** and Curl of **H**
- Dielectric and Magnetic Materials Compared
- Magnetic Susceptibility and Relative Permeability
- Boundary Conditions

Type of Magnetic Material

- (1) All materials are **diamagnetic**. The application of external magnetic field induces moments according to the Faraday induction law. This effect is usually imperceptible and it disappears upon removal of the external field.
- (2) In most atoms, the magnetic moments resulting from orbital and spinning motion of the electrons cancel. If the cancellation is not complete, the material is **paramagnetic**.
- (3) In some materials, the magnetization can be orders of magnitude larger than in either diamagnetic or paramagnetic substance. This material is **ferromagnetic**.

Magnetization \mathbf{M}

- The **magnetization \mathbf{M}** is the magnetic moment per unit volume of magnetized material at a point.
- If there are N atoms per unit volume, each possessing a magnetic dipole moment \mathbf{m} oriented in a given direction, then

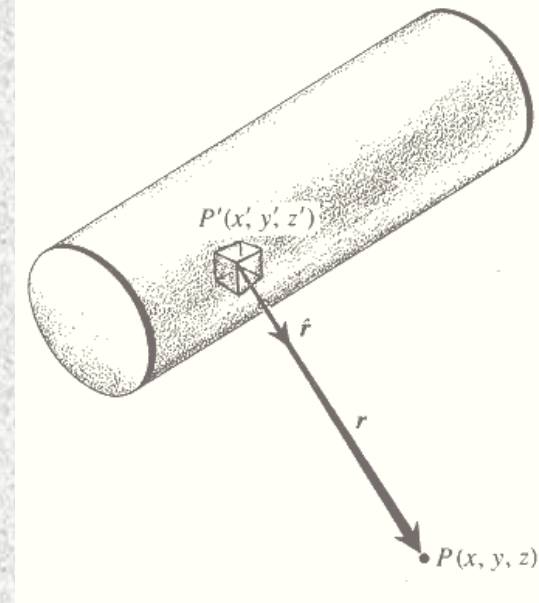
$$\mathbf{M} = N\mathbf{m}. \quad (20-1)$$

- The magnetization \mathbf{M} in magnetic media corresponds to the polarization \mathbf{P} in dielectric.
- The unit of magnetization is ampere per meter

Magnetic Field of A Magnetized Body

- Let us calculate \mathbf{B} at a point outside a magnetized body, as in figure.
- The vector potential at a point P located at a distance r from a current loop of magnetic moment \mathbf{m} is

$$\mathbf{A} = \frac{\mu_0}{4\pi} \frac{\mathbf{m} \times \hat{\mathbf{r}}}{r^2}. \quad (20-2)$$



- Then, for a volume v' of magnetized material,

$$\mathbf{A} = \frac{\mu_0}{4\pi} \int_{v'} \frac{\mathbf{M} \times \hat{\mathbf{r}}}{r^2} dv' = \frac{\mu_0}{4\pi} \int_{v'} \mathbf{M} \times \nabla' \left(\frac{1}{r} \right) dv'. \quad (20-3)$$

$$\mathbf{A} = -\frac{\mu_0}{4\pi} \int_{v'} \left(\nabla' \times \frac{\mathbf{M}}{r} \right) dv' + \frac{\mu_0}{4\pi} \int_{v'} \frac{\nabla' \times \mathbf{M}}{r} dv' \quad (20-4)$$

$$= \frac{\mu_0}{4\pi} \int_{\mathcal{A}'} \frac{\mathbf{M} \times \hat{\mathbf{n}}}{r} d\mathcal{A}' + \frac{\mu_0}{4\pi} \int_{v'} \frac{\nabla \times \mathbf{M}}{r} dv', \quad (20-5)$$

- It is clear that the vector potential in the neighborhood of a piece of magnetized material is the same as if one had volume and surface current densities. These equivalent currents are;

$$\mathbf{J}_e = \nabla \times \mathbf{M} \quad \text{and} \quad \mathbf{a}_e = \mathbf{M} \times \hat{n}. \quad (20-6)$$

- More generally;

$$\mathbf{A} = \frac{\mu_0}{4\pi} \int_{v'} \left(\mathbf{J}_f + \frac{\partial \mathbf{P}}{\partial t} + \nabla \times \mathbf{M} \right) dv', \quad (20-7)$$

- Thus a more general form of the Biot-Savart law

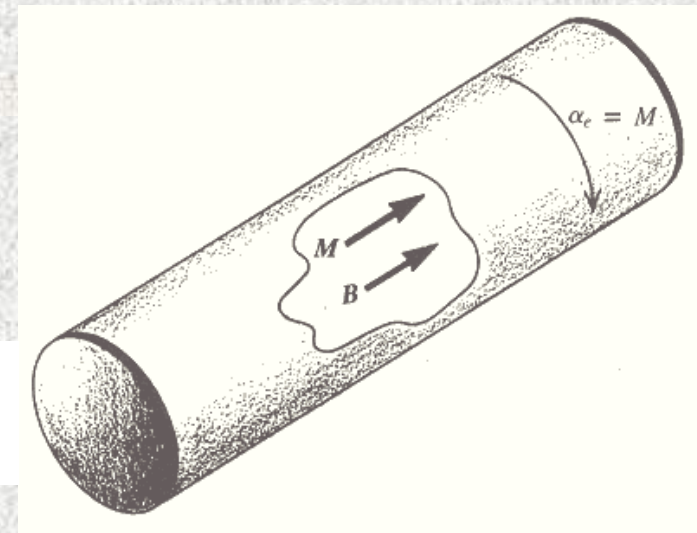
$$\mathbf{B} = \frac{\mu_0}{4\pi} \int_{v'} \frac{(\mathbf{J}_f + \partial \mathbf{P} / \partial t + \nabla \times \mathbf{M}) \times \hat{r}}{r^2} dv'. \quad (20-8)$$

Divergence of \mathbf{B} in Presence of Magnetic Material

- The magnetif fields originate either in the macroscopic motion of charge or in equivalent current.
- The relation

$$\nabla \cdot \mathbf{B} = 0$$

(20-9)



applies even in the presence of magnetic materials.

- This is one of Maxwell's equations.

The Magnetic Field Strength \mathbf{H} and $\nabla \times \mathbf{H}$

- For the static fields in the absence of magnetic materials

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}_f. \quad (20-10)$$

- \mathbf{J}_e is the current density related to the motion of free charges.
- In the presence of magnetized materials,

$$\nabla \times \mathbf{B} = \mu_0 (\mathbf{J}_f + \mathbf{J}_e). \quad (20-11)$$

$$\nabla \times \mathbf{B} = \mu_0 (\mathbf{J}_f + \nabla \times \mathbf{M}), \quad (20-12)$$

$$\nabla \times \left(\frac{\mathbf{B}}{\mu_0} - \mathbf{M} \right) = \mathbf{J}_f. \quad (20-13)$$

- The vector within the parenthesis called **magnetic field strength**

$$\mathbf{H} = \frac{\mathbf{B}}{\mu_0} - \mathbf{M}. \quad (20-14)$$

- Both **H** and **M** are expressed in amperes / meter. Thus

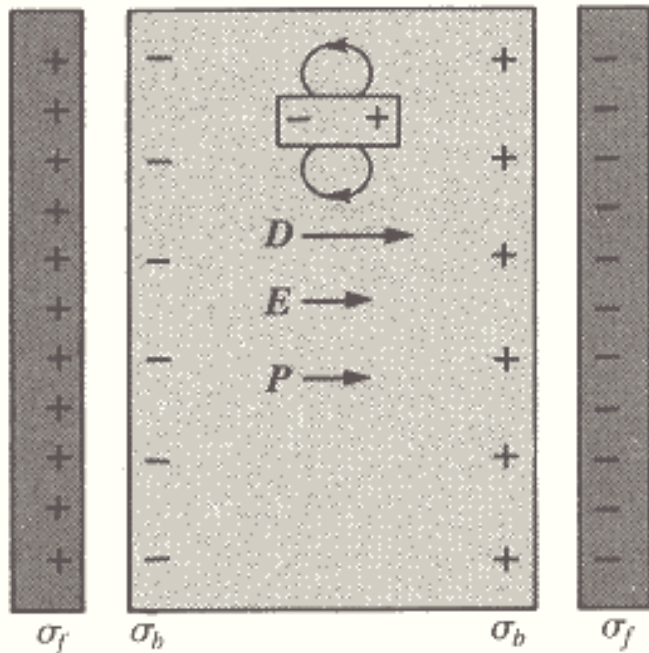
$$\mathbf{B} = \mu_0(\mathbf{H} + \mathbf{M}) \quad (20-15)$$

- And even inside the magnetized material,

$$\nabla \times \mathbf{H} = \mathbf{J}_f \quad (20-16)$$

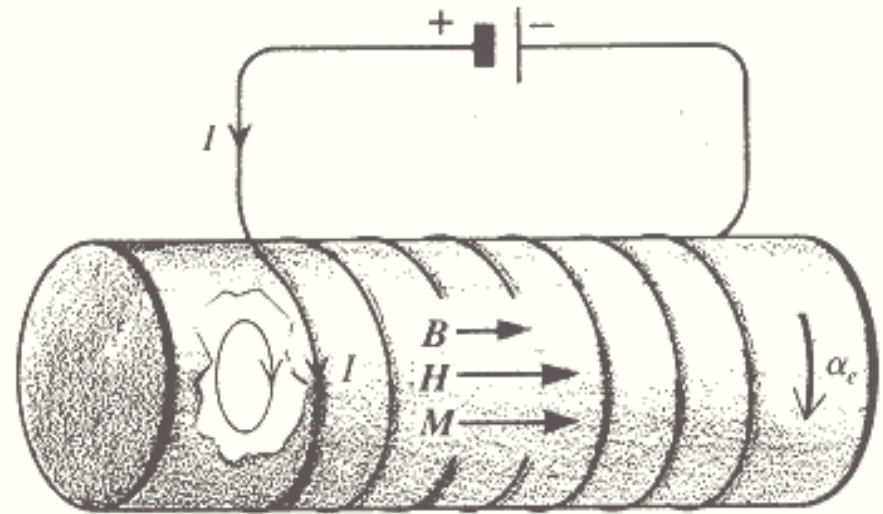
- It must be remembered that above equation is only valid in static fields

Dielectric and Magnetic Material Compared



$$E = \frac{1}{\epsilon_0}(D - P)$$

(a)



$$B = \mu_0(H + M)$$

(b)

- In dielectric E is smaller because the field of the bound charges opposes that of the free charges
- In magnetic material, \mathbf{B} is larger because the field of the equivalent current aids that of the free current

Ampere's Circuital Law in Presence of Magnetic Material

- Let us integrate below equation over an open surface of area A bounded by a curve C

$$\nabla \times \mathbf{H} = \mathbf{J}_f \quad (20-16)$$

- We found:

$$\int_{\mathcal{A}} (\nabla \times \mathbf{H}) \cdot d\mathcal{A} = \int_{\mathcal{A}} \mathbf{J}_f \cdot d\mathcal{A}, \quad (20-18)$$

- Using Stokes theorem on the left-hand side,

$$\oint_C \mathbf{H} \cdot d\mathbf{l} = I_f, \quad (20-19)$$

- Note that I_f does not include the equivalent currents. It can serve to calculate \mathbf{H} even in the presence of magnetic materials. This is valid for only steady currents

Magnetic Susceptibility (χ_e) and Relative Permeability μ_r

- It is convenient to define magnetic susceptibility χ_m such that

$$\mathbf{M} = \chi_m \mathbf{H}. \quad (20-21)$$

- Then

$$\mathbf{B} = \mu_0(\mathbf{H} + \mathbf{M}) = \mu_0(1 + \chi_m)\mathbf{H} = \mu_0\mu_r\mathbf{H} = \mu\mathbf{H}, \quad (20-22)$$

- where

$$\mu_r = 1 + \chi_m \quad (20-23)$$

- is the relative permeability, and

$$\mu = \mu_r\mu_0 \quad (20-24)$$

- is the permeability of a material. Thus

$$\mathbf{M} = \chi_m \frac{\mathbf{B}}{\mu}. \quad (20-25)$$

Boundary Condition

- Both **B** and **H** obey boundary conditions at the interface between two media
- The net outward flux of **B** through any closed surface is zero

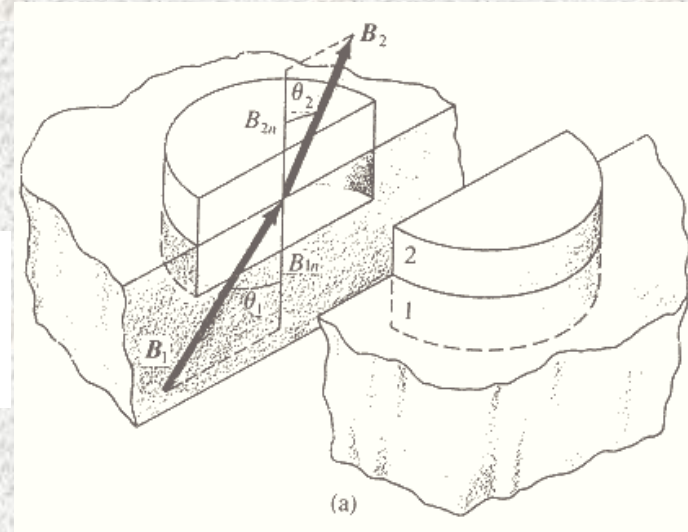
$$\int_{\mathcal{A}} \mathbf{B} \cdot d\mathcal{A} = 0.$$

(18-18)

- Then the normal component of **B** is continuous across an interface

$$B_{1n} = B_{2n}.$$

(20-26)



- Form the circuital law, the line integral of $\mathbf{h} \cdot d\mathbf{l}$ around a path is equal to the current I linking the path

$$\oint_C \mathbf{H} \cdot d\mathbf{l} = I_f, \quad (20-19)$$

- At the interface, if the current is zero then the tangential component of \mathbf{H} is continuous across the interface

$$H_{1t} = H_{2t}. \quad (20-27)$$

- Setting $\mathbf{B} = \mu\mathbf{H}$ for both media, Then

$$\frac{\tan \theta_1}{\tan \theta_2} = \frac{\mu_{r1}}{\mu_{r2}}. \quad (20-28)$$

